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ABSTRACT

The emergence of tilted bipolar active regions (ARs) and the dispersal of their flux, mediated via processes such as diffusion, differential rotation, and meridional circulation, is believed to be responsible for the reversal of the Sun's polar field. This process (commonly known as the Babcock-Leighton mechanism) is usually modeled as a near-surface, spatially distributed α -effect in kinematic mean-field dynamo models. However, this formulation leads to a relationship between polar field strength and meridional flow speed which is opposite to that suggested by physical insight and predicted by surface flux-transport simulations. With this in mind, we present an improved double-ring algorithm for modeling the Babcock-Leighton mechanism based on AR eruption, within the framework of an axisymmetric dynamo model. Using surface flux-transport simulations, we first show that an axisymmetric formulation-which is usually invoked in kinematic dynamo models-can reasonably approximate the surface flux dynamics. Finally, we demonstrate that our treatment of the Babcock-Leighton mechanism through double-ring eruption leads to an inverse relationship between polar field strength and meridional flow speed as expected, reconciling the discrepancy between surface flux-transport simulations and kinematic dynamo models.

Key words: Sun: activity - Sun: dynamo - Sun: interior

Online-only material: color figures

1. INTRODUCTION

Currently, some of the best tools for understanding the solar magnetic cycle are axisymmetric kinematic dynamo models and surface flux-transport simulations. On the one hand, kinematic dynamo models (which are usually based on an axisymmetric formulation) attempt to model the magnetic cycle self-consistently by using a prescribed meridional flow, differential rotation, turbulent diffusivity, and poloidal source (see Section 5). They have been successful in reproducing several of the characteristics of the solar cycle (see, for example, Choudhuri et al. 1995; Durney 1997; Dikpati & Charbonneau 1999; Covas et al. 2000; Nandy & Choudhuri 2001; Rempel 2006; Guerrero & de Gouveia Dal Pino 2007: Jouve & Brun 2007: Muñoz-Jaramillo et al. 2009, MNM09 from here on; for more information about kinematic dynamo models see the review by Charbonneau 2005). On the other hand, surface flux-transport simulations study the evolution of the photospheric magnetic field by integrating the induction equation using a prescribed meridional flow, differential rotation, and turbulent diffusivity. There are two main differences between surface flux-transport simulations and kinematic dynamo models: in the former the computational domain is restricted to the surface (without imposing axisymmetry) and they are not self-excited, but driven by the deposition of active region (AR) bipolar pairs. This type of models has proved a successful tool for understanding surface dynamics on long timescales (see, for example, Mackay et al. 2002; Wang et al. 2002a; Schrijver et al. 2002) and the evolution of the coronal and interplanetary magnetic field (see, for example, Lean et al. 2002; Yeates et al. 2008). However, a discrepancy exists between kinematic dynamo models and surface flux-transport simulations regarding the relationship between meridional flow amplitude and the strength of the polar

field (Schrijver & Liu 2008; Hathaway & Rightmire 2010; Jiang et al. 2010). On the one hand, kinematic dynamo models find that a stronger meridional flow results in stronger polar field (Dikpati et al. 2008); on the other hand, surface flux-transport simulations find an inverse relationship (Wang et al. 2002b; Jiang et al. 2010). In this work, we improve upon the idea proposed by Durney (1997) and further elucidated by Nandy & Choudhuri (2001) of using axisymmetric ring doublets to model individual ARs. We show that this captures the surface dynamics better than the α -effect formulation and resolves the discrepancy between dynamo models and surface flux-transport simulations regarding the relationship between meridional flow speed and polar field strength.

2. EVOLUTION OF THE AXISYMMETRIC COMPONENT OF THE MAGNETIC FIELD ON TIMESCALES COMPARABLE TO THE SOLAR CYCLE

As mentioned before, kinematic dynamo models are usually based on an axisymmetric formulation and our model is not an exception. Given that here we introduce an improved axisymmetric double-ring algorithm for modeling AR eruptions (see below), but AR emergence is strictly a non-axisymmetric process, it is important to study the amount of information lost by averaging over the longitudinal dimension. We do this by performing surface transport simulations driven by a synthetic set of AR cycles based on Kitt Peak data using the model of Yeates et al. (2007). We perform a regular surface fluxtransport simulation in which the bipolar ARs are distributed all across the surface of the Sun (Case 1) and another in which the same set of ARs is deposited at the same Carrington longitude while leaving other properties (time, tilt, latitude of emergence, and flux) intact (Case 2). The difference between the two



Figure 1. Long-term evolution of the photospheric magnetic field in surface flux-transport simulations: (a) snapshot of the magnetic field at the peak of the cycle for Case 1 (ARs deposited at all longitudes). (b) Snapshot of the magnetic field at the peak of the cycle for Case 2 (ARs deposited at a single longitude). (c) Butterfly diagram for Case 1. (d) Butterfly diagram for Case 2. (e) Difference between the butterfly diagrams of Case 1 and Case 2. (f) Longitudinal average of the snapshots shown in the top row, taken at the peak of the cycle.

(A color version of this figure is available in the online journal.)

simulations is clear from the top row of Figure 1, where we show a snapshot of the surface magnetic field at the peak of the cycle for Case 1 (Figure 1(a)) and Case 2 (Figure 1(b)). Obviously these cases have entirely different magnetic configurations at the time of deposition. However, when the magnetic field is averaged in longitude and stacked in time to create a magnetic synoptic map (also know as butterfly diagram, Figures 1(c) and (d)), a careful examination shows that the results are essentially the same within a margin of 1% (Figures 1(e) and (f)). The reason the simulations have identical outcomes is that the differential rotation and the meridional flow are both independent of longitude in the simulations. Note that non-axisymmetry is essential for the evolution of the coronal and interplanetary magnetic field. This result simply indicates that an axisymmetric representation of surface dynamics is a reasonable approximation if we are only concerned with the general properties of the magnetic field at the surface over solar cycle timescales in the context of dynamo models.

3. MODELING INDIVIDUAL ACTIVE REGIONS AS AXISYMMETRIC DOUBLE RINGS

The initial implementation of the double-ring algorithm by Durney (1997) and Nandy & Choudhuri (2001) consisted in searching the bottom of the convection zone (CZ) for places in which the toroidal field exceeds a buoyant threshold and placing two axisymmetric rings of constant radial flux directly above them. This implementation had two important deficiencies: strong sensitivity to changes in grid resolution and the introduction of sharp discontinuities in the ϕ component of the vector potential. The first necessary step to address these problems is a careful mathematical definition of the vector potential associated with each ring doublet, which ensures a continuous first derivative in the computational domain. We do so by building a separable function:

$$A_{\rm ar}(r,\theta) = K_0 A(\Phi) F(r) G(\theta), \tag{1}$$

where K_0 is a constant we introduce to ensure super-critical solutions and $A(\Phi)$ defines the strength of the ring doublet. F(r) is defined as

$$F(r) = \begin{cases} 0 & r < R_{\odot} - R_{\rm ar} \\ \frac{1}{r} \sin^2 \left[\frac{\pi}{2R_{\rm ar}} (r - (R_{\odot} - R_{\rm ar})) \right] & r \ge R_{\odot} - R_{\rm ar} \end{cases},$$
(2)

where $R_{\odot} = 6.96 \times 10^8$ m corresponds to the radius of the Sun and $R_{\rm ar} = 0.85 R_{\odot}$ represents the penetration depth of the AR. This depth is motivated from results indicating that the disconnection of an AR flux tube happens deep down in the CZ



Figure 2. (a) Diagram illustrating the quantities which define the latitudinal dependence of a double-ring bipolar pair. (b) Poloidal field lines of one of our double rings including a potential field extrapolation for the region outside the Sun. The dashed line marks the location of the penetration depth R_{ar} . (A color version of this figure is available in the online journal.)

(Longcope & Choudhuri 2002). $G(\theta)$, on the other hand, is easier to define in integral form:

$$G(\theta) = \frac{1}{\sin\theta} \int_0^{\theta} \left[B_-(\theta') + B_+(\theta') \right] \sin(\theta') d\theta', \qquad (3)$$

where $B_+(B_-)$ defines the positive (negative) ring:

$$B_{\pm}(\theta) = \begin{cases} 0 \quad \theta < \theta_{\rm ar} \mp \frac{\chi}{2} - \frac{\Lambda}{2} \\ \pm \frac{1}{\sin(\theta)} \left[1 + \cos\left(\frac{2\pi}{\Lambda} \left(\theta - \theta_{\rm ar} \pm \frac{\chi}{2}\right)\right) \right] \\ \theta_{\rm ar} \mp \frac{\chi}{2} - \frac{\Lambda}{2} \leqslant \theta < \theta_{\rm ar} \mp \frac{\chi}{2} + \frac{\Lambda}{2} \\ 0 \quad \theta \geqslant \theta_{\rm ar} \mp \frac{\chi}{2} + \frac{\Lambda}{2}. \end{cases}$$
(4)

Here θ_{ar} is the co-latitude of emergence, Λ is the diameter of each polarity of the doublet for which we use a fixed value of 6° (heliocentric degrees), and $\chi = \arcsin[\sin(\gamma)\sin(\Delta_{ar})]$ is the latitudinal distance between the centers, which in turn depends on the angular distance between polarity centers $\Delta_{ar} = 6^{\circ}$ and the AR tilt angle γ ; χ is calculated using the spherical law of sines (see Figure 2(a) for a diagram illustrating these quantities). Figure 2(b) shows the axisymmetric signature of one of such axisymmetric ARs.

4. RECREATING THE POLOIDAL FIELD

Given that the accumulated effect of all ARs is what regenerates the poloidal field, we need to specify an algorithm for AR eruption and decay in the context of the solar cycle. On each solar day of our simulation, we randomly chose one of the latitudes with fields higher than a buoyancy threshold of $B_c = 5 \times 10^4$ G at the bottom of the CZ ($r = 0.71 R_{\odot}$) and calculate the amount of magnetic flux present within its associated toroidal ring. The probability distribution we use is not uniform, but is restricted to observed active latitudes. We do this by making the probability function drop steadily to zero between $30^{\circ} (-30^{\circ})$ and 40° (-40°) in the northern (southern) hemisphere:

$$P(\theta) \propto \left(1 + \operatorname{erf}\left[\frac{\theta - 0.305\pi}{0.055\pi}\right]\right) \left(1 - \operatorname{erf}\left[\frac{\theta - 0.694\pi}{0.055\pi}\right]\right).$$
(5)

We then calculate the corresponding AR tilt, using the local field strength B_0 , the calculated flux Φ_0 , and the latitude of emergence λ . For this we use the expression found by Fan et al. (1994):

$$\gamma \propto \Phi_0^{1/4} B_0^{-5/4} \sin(\lambda), \tag{6}$$

reducing the magnetic field of the toroidal ring from which the AR originates. In order to do this, we first estimate how much magnetic energy is present on a partial toroidal ring (after removing a chunk with the same angular size as the emerging AR). Given that this energy is smaller than the one calculated with a full ring, we set the value of the toroidal field such that the energy of a full toroidal ring filled with the new magnetic field strength is the same as the one calculated with the old magnitude for a partial ring. Finally, we deposit a double ring (as defined in Section 3) with these calculated properties, at the chosen latitude.

5. THE KINEMATIC MEAN-FIELD DYNAMO MODEL

We perform dynamo simulations to explore how the doublering formulation compares to the near surface α -effect formulation. In particular, we focus on the relationship between meridional flow speed and polar field strength. Our model is based on the axisymmetric dynamo equations:

$$\frac{\partial A}{\partial t} + \frac{1}{s} [\mathbf{v}_{p} \cdot \nabla(sA)] = \eta \left(\nabla^{2} - \frac{1}{s^{2}}\right) A + \alpha_{0} f(r, \theta) F(B_{tc}) B_{tc}$$
(7)
$$\frac{\partial B}{\partial t} + s \left[\mathbf{v}_{p} \cdot \nabla \left(\frac{B}{s}\right)\right] + (\nabla \cdot \mathbf{v}_{p}) B = \eta \left(\nabla^{2} - \frac{1}{s^{2}}\right) B + s([\nabla \times (A\hat{\mathbf{e}}_{\phi})] \cdot \nabla \Omega) + \frac{1}{s} \frac{\partial(sB)}{\partial r} \frac{\partial \eta}{\partial r},$$
(8)

where A is the ϕ component of the vector potential (from which B_r and B_{θ} can be obtained), B is the toroidal field (B_{ϕ}) , v_p is the meridional flow, Ω is the differential rotation, η is the turbulent magnetic diffusivity, and $s = r \sin(\theta)$. The second term on the right-hand side of Equation (7) corresponds to the poloidal source in the mean-field formulation. In this formulation, α_0 is a constant that sets the strength of the source term and is usually used to ensure super-critical solutions; $\alpha(r, \theta)$ captures the spatial properties of the Babcock–Leighton

Double-ring Algorithm

 α -effect Formulation



Figure 3. Comparison between surface dynamics as captured by the double-ring algorithm (left column) and the α -effect formulation (right column). The top row shows the evolution of the surface magnetic field in the form of synoptic maps—the color map is saturated to enhance the visibility of the field at mid to low latitudes. The bottom row shows a snapshot of the poloidal components of the magnetic field taken at solar max. The solid contours correspond to clockwise field lines, the dashed contours correspond to counterclockwise field lines. The thick dashed lines mark the location of the tachocline. (A color version of this figure is available in the online journal.)

(BL) mechanism: confinement to the surface, observed active latitudes, and latitudinal dependence of tilt, while $F(B_{tc})$ adds nonlinearity to the dynamo by quenching the source term for values of the toroidal field at the bottom of the CZ B_{tc} that are too strong or too weak. More information about this source can be found in MNM09. Note that for simulations using the double-ring algorithm, this term is not present in the equations ($\alpha_0 = 0$).

In order to integrate these equations, we need to prescribe four ingredients: meridional flow, differential rotation, the poloidal field regeneration mechanism, and turbulent magnetic diffusivity. For the differential rotation, we use the analytical form of Charbonneau et al. (1999) with a tachocline centered at $0.7 R_{\odot}$ whose thickness is $0.05 R_{\odot}$ and we use the meridional flow profile defined in MNM09. This meridional flow better captures the features present in helioseismic data, especially the latitudinal dependence. We use an amplitude of 20 m s⁻¹ for the results shown in Figure 3 and a variable amplitude for the results shown in Figure 5 (see below). We use a double stepped diffusivity profile as described in MNM09. It starts with a diffusivity value $\eta_{bcd} = 10^8 \text{ cm}^2 \text{ s}^{-1}$ at the bottom of the CZ, jumps to a value of $\eta_{cz} = 10^{11} \text{ cm}^2 \text{ s}^{-1}$ in the near-surface layers. The first step is centered at $r_{\rm cz} = 0.71 R_{\odot}$ and has a half-width of $d_{\rm cz} = 0.015 R_{\odot}$ and the second step is centered at $r_{\rm sg} = 0.95 R_{\odot}$ and has a half-width of $d_{\rm sg} = 0.025 R_{\odot}$.

For the poloidal field regeneration mechanism, we use the improved ring-doublet algorithm described above, using a value of $K_0 = 400$, in order to insure super-criticality (for a meridional flow of 30 m s⁻¹). For those simulations which use an α -effect formulation, we use the non-local poloidal source described above (more information in MNM09) using a value of $\alpha_0 = 0.25$, in order to insure super-criticality (for a meridional flow of 30 m s⁻¹).

6. ADDRESSING THE DISCREPANCY BETWEEN KINEMATIC DYNAMO MODELS AND SURFACE FLUX-TRANSPORT SIMULATIONS

In order to have a net accumulation of unipolar field at the poles, it is necessary to have an equal amount of flux cancellation across the equator. Since the meridional flow is poleward in the top part of the CZ, it essentially acts as a barrier against flux cancellation by sweeping both positive and negative AR polarities toward the poles resulting in weak polar fields. This leads to an inverse correlation between flow speed and polar field strength which is accurately captured in surface flux-transport



Figure 4. Diagram for the evolution of the meridional flow amplitude with respect to the sunspot cycle: each solar cycle *N* has a unique meridional flow strength v_n which is randomly chosen between 15 and 30 m s⁻¹. Additionally, the polar field strength B_r of cycle *N* is measured at the end of it. (A color version of this figure is available in the online journal.)

simulations. Contrarily, dynamo simulations in typically used parameter regimes obtain an opposite relationship that is not consistent with the above physics. This is because if there is already a strong separation of flux, a fast meridional flow will lead to an enhancement of the polar field due to flux concentration. This unrealistically strong separation is typical of kinematic dynamo models that use a non-local α -effect BL source (see Figure 3(c)). The reason is that by increasing the vector potential A proportionally to the toroidal field B at the bottom of the CZ (Equation (7)), one creates strong gradients in the vector potential above the edges of the toroidal field belt; this ends up immediately producing a poloidal field which is as large in length scale as the toroidal field itself, circumventing the whole process of flux transport by circulation and diffusion. Figure 3 illustrates this fundamental difference. The top row shows the evolution of the surface magnetic field for a dynamo model using the double-ring algorithm (Figure 3(a)) versus one using the α -effect formulation (Figure 3(b)). The different ways in which each formulation handles the surface dynamics are evident. The double-ring simulation clearly shows a mixture of polarities and small-scale features which migrate to the poles (very much like the observed evolution of the surface magnetic field). On the other hand, the mean-field formulation only shows two large-scale polarities whose centroids drift apart as the cycle progresses. The bottom row depicts a snapshot of the poloidal field for the double-ring algorithm (Figure 3(c)) and the α -effect formulation (Figure 3(d))—both snapshots taken at solar max. Here the presence of small-scale features and a mixture of polarities is evident for the double ring, whereas the α -effect formulation only shows a large-scale magnetic field with two polarities. It is clear that although the large-scale internal field is similar for both, the double-ring algorithm does a much better job of capturing the surface dynamics.

6.1. Polar Field Strength versus Meridional Flow Speed

In order to study the relationship between meridional flow and polar field strength, we perform simulations in which we randomly change the meridional flow amplitude from one sunspot cycle to another (between 15 and 30 m s⁻¹). This is illustrated in Figure 4 where a series of sunspot cycles is plotted along with their associated meridional flow. We then evaluate the correlation between the amplitude of the meridional flow of a given cycle and the polar field strength B_r at the end of it. Since we want to evaluate the relative performance of the double-ring algorithm as opposed to the non-local BL source, we perform the same simulation for both types of sources. Aside from the varying meridional flow amplitude and the poloidal source, the rest of the ingredients are the same. It is important to note that partly due to difficulties in tracking the exact occurrence of solar minimum, the two hemispheres eventually drift out of phase in long simulations—sometimes this phase difference leads to quadrupolar solutions which often go back to the observed dipolar solution. This parity issue only appears when the meridional flow is changed at solar minimum: if there are no variations, or if the variation takes place at solar maximum, the cycle is always locked in phase with dipolar parity. Nevertheless, to compare our simulations with surface flux-transport models, we change the flow speed only at solar minimum. To be consistent, we accumulate statistics only from cycles in which the two hemispheres are in dipolar phase. The statistics performed for both types of source contain about 200 sunspot cycles.

The values of polar field we find using the kinematic dynamo simulations are of the order of 10 kG which is a common feature of dynamo models, which are successful in simulating the strong toroidal field necessary to produce sunspots and sustain the solar cycle (Dikpati & Charbonneau 1999; Chatterjee et al. 2004; Jiang & Wang 2007; Jouve et al. 2008). Recent high-resolution observations of the polar region have now confirmed the existence of such strong kilo-Gauss unipolar flux tubes (Tsuneta et al. 2008). Figure 5 shows the results of both simulations. We find a weak positive correlation between meridional flow and polar field strength for the simulations using the non-local α -effect formulation (Figure 5, top), which is in general agreement with the results of Dikpati et al. (2008). On the other hand, the simulations using the double-ring formulation distinctively show a negative correlation (Figure 5, bottom), in agreement with surface flux-transport simulations (Wang et al. 2002b). This clearly establishes that the discrepancy between the models is resolved by introducing the double-ring algorithm and that the double-ring formalism does a better job at capturing the observed surface magnetic field dynamics than the non-local α -effect formalism.

7. CONCLUDING REMARKS

In the first half of this work, we perform surface flux-transport simulations to test the validity of the axisymmetric formulation of the kinematic dynamo problem. Our results suggest that this axisymmetric formulation captures well the surface flux dynamics over spatial and temporal scales that are relevant for the solar cycle. Building upon this, we introduce an improved version of the double-ring algorithm to model the Babcock-Leighton mechanism for poloidal field regeneration in axisymmetric, kinematic dynamo models. We show that this new double-ring formulation generates surface field evolution and polar field reversal which is in close agreement with observations. Additionally, we find that this improved treatment of the Babcock–Leighton process generates an inverse relationship between meridional flow speed and polar field strength-which is suggested by simple physical arguments and also predicted by surface flux-transport simulations. This resolves the discrepancy between kinematic dynamo models and surface flux-transport simulations regarding the dynamics of the surface magnetic field. Since the latter drives the evolution of the corona and the heliosphere, our work opens up the possibility of coupling



Double-ring algorithm



Figure 5. Relationship between randomly varying meridional flow speed and polar field strength for simulations using the mean-field formulation (top row) vs. simulations using the double-ring algorithm (bottom row). The polar field strength (in Gauss) is represented by the maximum amplitude of the polar radial field (B_r) attained during solar minimum. The relationship between the above parameters is determined by the Spearman's rank correlation coefficient. Top row: correlation coefficient, r = 0.325; confidence, p = 99.99%. Bottom row: r = 0.625, p = 99.99%.

(A color version of this figure is available in the online journal.)

dynamo models of the solar cycle with coronal and heliospheric field evolution models.

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