- 1 The importance of accurately representing submerged vegetation morphology in the numerical
- 2 prediction of complex river flow
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10 Abstract:

This paper reports a novel method for the incorporation of complex plant 11 morphologies into a computational fluid dynamics (CFD) model, allowing the 12 numerical prediction of flows around individual plants. The morphological 13 complexity, which comprises the vertical and lateral distribution of individual 14 branches and leaves is captured through terrestrial laser scanning (TLS) and is 15 maintained in the numerical prediction of flow fields. This is achieved where the 16 post-processed, voxelised plant representation is incorporated into a CFD scheme 17 18 through a mass flux scaling algorithm (MFSA). Flow around *Prunus laurocerasus* has been modelled under foliated and defoliated states following the removal of 19 The complex plant morphologies are shown to produce spatially 20 leaves. heterogeneous downstream velocity fields, with velocity profiles that deviate 21 22 significantly from the idealised inflected shape. Rapid transition between the high velocity free stream zone and the zone of reduced velocity in the plant wake indicate 23 shearing of flow, with the point of reattachment extending up to seven plant lengths 24

25 downstream. The presence of leaves significantly modifies the flow field response, with development of a second, more pronounced wake structure around the dense 26 foliage. This approach provides a full flow numerical description of the pressure 27 field, enabling the vegetative drag force to be quantified. For the example given 28 here, drag force is an order of magnitude greater for the foliated state. The 29 methodology outlined here demonstrates the importance of accurately representing 30 complex plant morphology in hydraulic models, and allows drag forces and 31 coefficients to be calculated for specific plant species. 32

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34 Keywords:

35 CFD, Channel vegetation, Terrestrial Laser Scanning, Drag coefficient

36 *Introduction:*

Vegetation is abundant in lowland rivers and has a profound influence on the fluvial 37 system. It affects the mean and turbulent flow field (Nepf, 2012a), provides habitat, 38 alters light availability and temperature, and regulates concentrations of oxygen, 39 carbon, and nutrients (Carpenter and Lodge, 1986). A correct understanding of the 40 influence of vegetation on flow is therefore essential and in particular its contribution 41 as an additional form of flow resistance (Kadlec, 1990). Increased flow resistance 42 produces higher water levels per unit discharge, thus increasing the risk of flooding. 43 However, a numerical description of the flow around river channel vegetation 44 45 canopies is challenging given the multitude of scales to be considered (Nepf, 2012b) and the species-specific nature of plant morphology, which adds further complexity 46 to the quantification of vegetative flow resistance (Aberle and Järvelä, 2013; Folkard, 47 2011b; Green, 2006; Kouwen and Unny, 1973). 48

49 In vegetated flows, the canopy is defined as the above ground part of the plant stand consisting of all branches, stems, leaves and stipes (Paul et al., 2014). 50 One approach to define canopy geometry is based on the size of the individual stems and 51 blades, and the number of these elements per bed area (Nepf, 2012a). It is 52 assumed that if the canopy elements have a characteristic diameter, d, and an 53 average spacing between elements, ΔS , then the frontal area per canopy volume is 54 $A = d/\Delta S^2$. For foliated vegetation types, this is defined as the leaf area index (e.g., 55 Kaimal and Finnigan, 1994) and when integrated over the plant height, the canopy 56 density (λf) is predicted from the frontal area per bed area, also known as the 57 roughness density (Wooding et al., 1973). However, aquatic canopies exhibit a wide 58 range of morphologies and densities (Leonard and Luther, 1995; Lightbody and 59 Nepf, 2006; Valiela et al., 1978), with stiffer, emergent plants tending to have 60

rounded stems and submerged grasses tending to have a blade geometry (Nepf,
2012a). Furthermore, variations in the size, shape and density of plant elements can
have a vertical dependence, which contribute towards the overall plant shape
(Wilson *et al.*, 2005). In natural settings, therefore, a considerable range of
vegetation morphologies exist.

This is further complicated where branches and leaves add to the total surface area, 66 therefore creating a greater obstacle to flow than the plant stem alone (Leonard and 67 Luther, 1995). Within the vegetation canopy flow is forced around each branch or 68 leaf so that the velocity field is spatially heterogeneous at the scale of these 69 70 elements. Vegetation structure, in particular the vertical and horizontal distribution of biomass, is therefore reported to control flow through, over and around vegetation 71 layers (Tempest et al., 2015). Furthermore, the velocity and driving forces within a 72 submerged canopy has a range of behaviour depending on the relative depth of 73 submergence (Nepf and Vivoni, 2000), defined as the ratio of flow depth, H, to 74 75 canopy height, h. In lowland river systems most submerged aquatic canopies occur in the range of shallow submergence H/h<5 (Chambers and Kaiff, 1985; Duarte, 76 1991), for which both turbulent stress and potential pressure gradients are important 77 78 in driving flow over the canopy.

Our current understanding of flows through shallow submerged vegetation comes from physically scaled flume models, field studies, and numerical modelling studies. Flume models have been used to provide a process-based understanding of complex canopy flows, and the drag processes that contribute towards the development of a mean velocity profile often described and approximated as Sshaped, or inflected (Nepf, 2012b). The representation of the vegetation in these laboratory experiments is crucial, with vegetation generally represented by: (i) artificial plants or surrogates, or (ii) scaled plants or natural plants (Frostick *et al.*,
2011).

At the simplest level, discrete, rigid cylindrical elements arranged in varying spatial 88 configurations have been used to represent specific attributes such as stem density 89 in stiff, emergent plants (Liu et al., 2008; Nepf, 1999). Conversely, polyethylene 90 strips have been used to represent the flexibility and reconfiguration commonly 91 observed in shallowly submerged species e.g. Mediterranean seagrass Posidonia 92 oceanica (Folkard, 2005; Folkard, 2011a). To replicate realistic structural 93 distributions of natural plants, artificial surrogates with an explicit parameterisation of 94 95 biomass have recently been used (Schoneboom et al., 2010). Often, however, artificial representations of vegetation neglect the horizontal and vertical variation in 96 plant structure observed in the natural prototype habitat, which can lead to the 97 98 incorrect predictions of flow at the plant and canopy scale (Tempest et al., 2015). Where natural vegetation is used (Järvelä, 2002; Sand-Jensen, 2003; Siniscalchi 99 100 and Nikora, 2012), samples can prove difficult to maintain under laboratory conditions and may not capture the variety of characteristics observed in vegetation 101 (Frostick et al., 2011). Misrepresentation of artificial or real vegetation morphology 102 would be translated into the flow field, and any simplification may therefore 103 compromise the representativeness of results, where alterations to the velocity and 104 pressure fields will have primary implications for the calculation of vegetative flow 105 106 resistance.

Field studies add further to our understanding, with the collection of threedimensional velocity fields around large woody debris (Daniels and Rhoads, 2003), and isolated patches of in-situ submerged macrophytes (Schoelynck *et al.*, 2013). Furthermore, the turbulence structure has been investigated around

heterogeneously distributed submerged macrophytes (Sukhodolov and 111 2010), and Sukhodolova, tree-centred emergent bars (Sukhodolov 112 and Sukhodolova, 2014). Although these studies provide great detail of the flow field, an 113 adequate quantification of the structure of the vegetation can prove difficult. 114

In high dimensional numerical modelling, vegetation has been represented by adding 115 a drag-related bulk source and sink term into the continuity equation (Fischer-Antze 116 et al., 2001; López and García, 2001). The drag force term is based on plant density 117 and an assumed rigid, cylindrical representation of vegetation, with a drag coefficient 118 of unity which is applicable for rigid cylinders with Reynolds numbers between 1×10^3 119 - 2x10⁵ (Cheng, 2013; Panton, 1984). These models reproduce mean and turbulent 120 flow, although they do not effectively predict the quantitative detail of turbulence 121 namely shear and wake scales (Defina and Bixio, 2005). Such an approach has 122 123 been further developed by dividing the drag into stem drag and leaf drag (Yue et al., 2007), where stem drag was modelled as above, but leaf drag was modelled 124 125 separately using an estimated leaf area index. An alternative approach is to include Stoesser et al. (2009, 2010) included an array of 126 individual vegetation stems. individually represented rigid cylinders using Large Eddy Simulation, and by using a 127 fine grid ensured that drag was directly accounted for, removing the need for 128 empirical drag coefficients. Several studies have sought to incorporate flexible 129 vegetation canopies. Ikeda et al. (2001) developed a biomechanical plant model 130 based upon the dynamic Euler-Bernoulli cantilever beam equation within a two 131 dimensional LES framework. Marjoribanks et al. (2014c) developed a similar model 132 within a three-dimensional LES framework to look at arrays of semi-rigid stems 133 within flows. Similar approaches have been developed for highly flexible vegetation 134 applying a N-pendula equation (e.g. Abdelrhman, 2007; Dijkstra and Uittenbogaard, 135

136 2010). However, in all of these approaches each plant is represented as a single137 stem and does not incorporate the complex plant morphology.

Here we report on a new methodology to incorporate a complex plant morphology 138 into a numerical model used to predict flow-vegetation interactions. We model the 139 three-dimensional velocity and pressure fields, at a high spatial resolution, around an 140 isolated laboratory plant stand. The plant is characterised by a complex morphology, 141 having a natural stem and leaf distribution. We model the flow around both a foliated 142 and defoliated representation of the plant, following manual removal of the foliage. 143 For this initial proof of concept work, a single plant stand has been selected to better 144 145 quantify the plant structure, and ensure any differences in the flow response can be attributed to the different foliation states, therefore enabling the resistance effects of 146 the leaf body to be quantified. 147

We describe a physically-based characterisation of vegetation using terrestrial laser 148 149 scanning (TLS) which is subsequently incorporated into a computational fluid dynamics (CFD) model by application of a mass flux scaling algorithm (Hardy et al., 150 2005). Application of TLS enabled a three-dimensional model of the vegetation to be 151 rapidly captured into a Cartesian digital framework; that was subsequently 152 incorporated into numerical discretisation. For the first time, the morphological 153 complexity of the vegetation is then directly represented within the CFD model, 154 enabling a high resolution prediction of the three-dimensional velocity and pressure 155 fields, and the improved estimation of the drag force acting on the plant. The wider 156 implications for flow and sediment transport modelling around morphologically 157 complex vegetation, and future methodological developments, are discussed. 158

159 *Methodology:*

160 Terrestrial Laser Scanning (TLS) and voxelisation

TLS has been used to acquire a three-dimensional representation of Prunus 161 laurocerasus, an invasive species to the United Kingdom increasingly recorded in 162 riparian zones. The evergreen shrub can reach heights of 6 m, with large (0.05-0.18 163 m) oblong-acute, glossy, dark-green leaves and pale green branches (Polunin and 164 Everard, 1969; Stace, 2010). *Prunus laurocerasus* was selected for scanning given 165 its complex branch and leaf structure, and its ability to survive in laboratory 166 conditions for prolonged periods. The woody shrub shares morphological similarities 167 to woody riverine vegetation species such as *Populus nigra*, typically found on gravel 168 bars (O'Hare et al., 2015). In this application, a RIEGL VZ-1000 scanner was used 169 in a controlled laboratory environment. The scanner has a beam divergence of 0.3 170 mrad, a field of view 100° x 360° and an effective measurement rate of up to 122 000 171 measurements per second. Scans were collected at a distance of 3 m, with π and θ 172 173 increments set to 0.012 degrees, controlling the horizontal and vertical alignment respectively. Riegl (2015) report that at a distance of 10 m, the scanner has a range 174 accuracy of 8 mm, and a precision of 5 mm. The scanner recorded multiple discrete 175 returns from a single emitted pulse, improving the interrogation of vegetation 176 elements (Pirotti et al., 2013), thereby heightening point density. To resolve issues 177 of occlusion, scans were acquired from four different perspectives to provide the 178 requisite overlap to capture the full three-dimensionality of the plant morphology 179 (Moorthy et al., 2008). 180

181 Scans were completed under foliated and defoliated states, following manual 182 removal of leaves (n = 432) (See Fig. 1). Individual point clouds were registered

using georeferenced reflective targets in RiSCAN PRO, supplemented by multi-183 station adjustment. Similar to the workflow of Jalonen et al. (2015) post-processing 184 was completed using CloudCompare software. After delineation of the area of 185 interest, erroneous data points were filtered using a statistical outlier removal tool 186 (SOR). The distance-weighted filter removed isolated points on the plant surface, 187 specifically those off-centre hits caused by the position and size of the laser pulse 188 189 footprint relative to the feature being scanned (Béland et al., 2014). By calculating the mean distance between each point in the initial point cloud and a neighbourhood 190 191 of its nearest points, and assuming a Gaussian distribution, those points which fall outside of a defined standard deviation threshold are regarded as outliers and 192 removed (Rusu et al., 2008). Following Jalonen et al. (2015), we calculate the mean 193 distance between every point and its 100 nearest neighbours, and remove those 194 points which fall outside of 1 standard deviation from the mean. Point clouds visually 195 196 match the actual plant morphology (Fig. 1a), containing ≈3 500 000 points in the foliated state (Fig. 1b), and ≈1 000 000 points in the defoliated state (Fig. 1c). A 197 198 characteristic subsection of the plant, (Fig. 1b and 1c), has been incorporated into the numerical model. This subsection shares the same morphological 199 characteristics (e.g. branch thickness, leaf density) as the remainder of the plant, but 200 allows flow to be solved at a higher spatial resolution in the modelling domain (see 201 below). 202

The millimetre scale spatial resolution of this point cloud exceeded what could feasibly be discretised within the CFD model, owing to the computational expense associated with solving flow at such high spatial resolutions. A simplification procedure following the gap fraction method of Straatsma *et al.* (2008) was applied, with subdivision of the scan into individual voxels (Béland *et al.*, 2011).

Morphological properties of vegetation have previously been established using either 208 spherical voxels (e.g., Antonarakis et al., 2010) or cubic voxels (e.g., Durrieu et al., 209 2008), however given the Cartesian grid structure of the CFD domain (see next 210 section), a cubic voxel representation was used. Voxelisation involved the fitting of 211 an octree structure with a user-defined maximum cell size (0.01 m) around the point 212 clouds, which captured the morphological complexity of the plant in both defoliated 213 and foliated states. The voxel size was justified given the branch diameter was in 214 the range 0.01-0.1 m, and therefore the voxel size closely approximated the finest 215 216 morphological elements. The voxelisation process is summarised for a subsample of the defoliated and foliated scans (Fig. 1b and 1c), outputting XYZ cell centroid 217 coordinates that are read directly into the CFD discretisation (see Fig. 2). 218

219 The numerical model

The numerical scheme involves a finite volume solution of the full three-dimensional 220 Navier-Stokes equations in a Cartesian coordinate system, with a Renormalized 221 Group Theory (RNG) k- ε turbulence model. The closure model is applied given the 222 large degree of fluid strain associated with flow around the plant as the RNG k-e 223 turbulence model calculates diffusion across the spectrum of scales (Yakhot and 224 Orszag, 1986). A hypothetical domain 350 cells long, 120 cells wide and 100 cells 225 high (4 200 000 grid cells) was created at a spatial resolution of 0.01 m. The 226 numerical simulations are run until the convergence criteria is met which is 227 dependent upon the mass conservation and momentum errors. In this application 228 the convergence criterion was set such that mass and momentum flux residuals 229 were reduced to 0.1% of the inlet flux. 230

A static representation of the plant, through the voxelised blockage, was represented 231 using the Mass Flux Scaling Algorithm (MFSA) (Hardy et al., 2005; Lane et al., 2002; 232 Lane et al., 2004). The MFSA has previously been used to represent flow over 233 complex topography such as gravel surfaces (Hardy et al., 2007), and idealised 234 single stemmed vegetation elements that are used to represent a vegetation canopy 235 (Marjoribanks et al., 2014c). The MFSA represents the plant as a numerical 236 porosity, and enables the voxelised plant to occupy a specified fraction of each grid 237 cell. For each grid cell a binary occupied/unoccupied porosity is defined because the 238 239 0.01 m voxel size is equal to that of the 0.01 m grid cell size. The voxelised blockage was incorporated 0.5 m downstream from the inlet (0.14 X/I), and centred 240 (0.5 Y/w). The bed was treated as a nonslip boundary using the logarithmic law of 241 242 the wall and domain side walls were considered frictionless boundaries. The vegetation-flow interface is treated as an immersed boundary. Inlet conditions are 243 held constant between the defoliated and foliated model runs with the downstream 244 velocity set to 0.25 m s⁻¹ with an inlet turbulent intensity of 5%. Thus, the flow was 245 assumed to be fully turbulent and subcritical. The outlet was defined using a fixed-246 pressure boundary condition where mass is allowed to enter and leave the domain. 247

248 **Results:**

Here we present the downstream (u-component) velocity field for the defoliated and 249 foliated cases (Fig. 2c and 2f) in plan view at 0.4 and 0.6 Z/h (Fig. 3a and 4a). 250 Under the defoliated state (Fig. 3a), individual stems introduce flow separation and 251 reattachment with the formation of narrow wakes of reduced velocity. At 0.4 Z/h, 252 coalescence of these wakes is observed. However, this behaviour varies vertically, 253 and at 0.6 Z/h, where the branches are spaced further apart, wakes behave 254 Wake coalescence would therefore depend on the separation independently. 255 distance between individual branches. Under the foliated scenario (Fig. 4a), a 256 257 single, more pronounced zone of flow separation and reattachment is evident, indicative of behaviour shown by a bluff object. In the foliated state, the shape of the 258 wake is vertically non-uniform, which is a function of the vertical and lateral 259 distribution of the plant morphology, and results in flow asymmetry. For example, at 260 0.4 Z/h the abundance of leaves at lower Y/w values produce an asymmetrical wake 261 structure that extends further downstream than the corresponding wake in the 262 defoliated state. For both the defoliated and foliated states similarities can be 263 observed; namely a reduction in velocity immediately upstream of the blockage, with 264 marginal flow acceleration around the blockage edges, indicative of flow in a junction 265 vortex system (Simpson, 2001). It is suggested that this canopy shear layer 266 turbulence is dominated by Kelvin-Helmholtz and Görtler-type vortices generated 267 through shear instability, which evolve with distance downstream of the plant 268 (Ghisalberti and Nepf, 2002). 269

The wake shape is further illustrated through a vertical slice down the midline (0.5 Y/w) (Fig. 3b and 4b). In both cases, wake shape varies considerably with Z/h. For the defoliated state, development of a wake zone at 0.2-0.4 Z/h corresponds with the

main branching point of the plant (see Fig. 2), with a concentration of branches. The 273 wake is inclined slightly upwards, thins in the downstream direction and extends ≈ 7 274 plant lengths downstream. Marginal flow acceleration is evident around the outer 275 edge of the central branch. A more complex wake structure consisting of two 276 discrete layers is evident in the foliated state. Again, the lower wake corresponds 277 with the branching point at 0.2-0.4 Z/h, although only extends ≈ 3 plant lengths 278 downstream. Above this, a pronounced and thicker wake zone at 0.45-0.65 Z/h 279 corresponds with the dense foliation, and extends \approx 7 plant lengths downstream. The 280 dense foliation component is influential in producing a localised velocity response. 281

The morphological complexity of the plant introduces additional flow heterogeneity, 282 therefore velocity profiles begin to deviate from the idealised inflected profiles that 283 are associated with canopy flows (Fig. 5a, inset graph). Fig. 5 provides evidence for 284 three distinct velocity zones in the vertical, namely: a zone of relative flow 285 acceleration beneath the bulk of the plant in the near bed region (sub-canopy flow), a 286 zone of flow acceleration above the plant in the free stream zone, and between 287 these a non-uniform low velocity zone associated with flow deceleration around the 288 289 plant blockage. The shape of the vertical velocity profiles clearly differ between the defoliated and foliated states. When defoliated, the velocity minima is positioned 290 lower in the flow depth, and associated with the point at which the main branch splits 291 292 into sub-branches (see Fig. 2). When foliated, however, the velocity minima is shifted higher in the flow, and associated with the main leaf body. The magnitude 293 and size of the low velocity zone in the foliated state is exaggerated relative to the 294 defoliated state, illustrating the important role of the leaf body in modifying the flow 295 disturbance. In both foliation states the accelerated sub-canopy flow component 296 297 appears to be similarly sized and shaped, indicating that distance between the bed and base of the main plant blockage influences the characteristics of this zone. The velocity profiles show that with increasing distance downstream, the flow begins to recover, with velocity profiles becoming more modulated, and velocities reverting towards the inlet velocity of 0.25 m s⁻¹.

Especially in the foliated state proximal to the blockage (Fig. 5a and Fig. 5b), a sharp 302 transition is evident between the reduced velocity zone and free stream zone, 303 characterised by flow acceleration, with this velocity discontinuity indicative of shear 304 layer formation and the presence of Kelvin-Helmholtz instabilities (Ghisalberti and 305 Nepf, 2002). The shear layer appears more prominent where the plant thickness is 306 larger and therefore the shear layer scales with the local plant thickness. Vortex 307 growth stops when turbulent energy production is equal to dissipation (Ghisalberti 308 and Nepf, 2004). 309

At the wake scale, mean kinetic energy is converted into wake-generated turbulent 310 kinetic energy at the scale of the plant stems (Ghisalberti and Nepf, 2002) and 311 therefore analysis of the turbulent kinetic energy (TKE) provides an estimation of the 312 amount of form drag introduced by the plant (Raupach and Shaw, 1982). Direct 313 comparisons between the defoliated and foliated states are shown at 0.45 Z/h (Fig. 314 6a and 6b). In both cases, zones of high TKE (> 0.04 m^2/s^2) are observed proximal 315 to the outer edge of the plant, driven by the forcing of flow around the blockage, 316 resulting in flow acceleration (u-component) and lateral movement (v-component). 317 For the defoliated state, these high TKE zones are enclosed around individual 318 branches, whereas in the foliated state the zones are comparably larger and extend 319 a greater distance from the vegetation front, due to a longer, more pronounced 320 disturbance to the *v*-component of velocity. Because of the complex, interacting 321

nature of the wakes in the defoliated state, the leeward zone of low TKE (< 0.015 m²/s²) is more fragmented and extends a greater distance downstream than in the foliated state. Again this demonstrates canopy shear layer instability, dominated by Kelvin-Helmholtz and Görtler-type vortices evolving with distance downstream of the plant.

Pressure fields are analysed to calculate the drag force and subsequent drag 327 coefficients acting on the plant (Marjoribanks, 2013). Fig. 7a and 7b show the 328 pressure fields at 0.45 Z/h. When defoliated, the high pressure zone located directly 329 upstream of the blockage is isolated about individual branches. When foliated, 330 however, this zone has coalesced to form a comparatively larger, single body 331 characterised by higher pressures. Similarly, downstream of the plant, isolated 332 zones of low pressure are associated with individual branches when defoliated, 333 334 compared with a much more pronounced and extended low pressure zone when foliated. 335

336 Calculation of drag forces

The drag force is calculated by integrating the difference in the pressure field acting normal to the vegetation surface over the entire lateral extent of the plant. We sum the difference in pressure from immediately upstream and downstream of the plant. This is achieved by applying a mask to the three-dimensional vegetation extent, and extracting pressure values from one cell upstream and one cell downstream of the mask:

$$F_d = \int_A (p_f - p_b) dA \tag{1}$$

where F_d is the drag force (N/m²), p_f is the pressure at the blockage front (Pa), p_b is 343 the pressure at the blockage back (Pa), and A is the frontal area (m^2) . In this 344 instance where the plant is represented by a 0.01 m voxel size, this gives a cell area 345 of 0.0001 m². To calculate the plant frontal area, we count the number of cells at the 346 blockage front, and multiply this by the cell area. A full discussion of the drag 347 calculation is provided by Marjoribanks et al. (2014b). Drag forces of 0.15 N/m² and 348 1.74 N/m² are calculated for the defoliated and foliated states respectively. This 349 order of magnitude difference is attributed to the influence of the additional 350 morphological complexity introduced by leaf elements, which result in a different flow 351 response as drag increases with foliage density (Wilson et al., 2003). As previously 352 observed, leaves are shown to introduce a second wake structure that extends ≈7 353 plant lengths downstream, resulting in a more spatially heterogeneous velocity field. 354 This corresponds with the more pronounced TKE patterns observed in the foliated 355 case, indicating a greater form drag contribution. Both of these factors result from 356 the greater number of blocked cells in the foliated state, imparting a greater 357

disturbance on the flow. The drag force values are of a similar order of magnitude to the direct measurements of vegetative drag force (\approx 0-10 N/m²), for small natural woody trees, undertaken by Jalonen and Järvelä (2014).

361 Drag forces are used to calculate a drag coefficient, following:

$$C_d = \frac{F_d}{\frac{1}{2}\rho u^2 A} \tag{2}$$

where C_d is the drag coefficient, ρ is the density (kg/m³), and u is the inlet velocity (m 362 s⁻¹). Drag coefficients are well understood for simple geometric shapes (e.g. 363 cylinders), but are less well understood for the complex geometries associated with 364 natural vegetation (Marjoribanks et al., 2014a). Modelling studies typically assign a 365 drag coefficient value of unity for vegetation, however this is only applicable to the 366 simplest reed and grass type plants. A value of unity is true for a single cylinder with 367 Reynolds numbers between 1×10^3 - 2×10^5 , although deviates significantly for more 368 complex vegetation as it is a function of both vegetation density and stem Reynolds 369 number (Tanino and Nepf, 2008). For sparsely configured leafy shrub communities, 370 the flume experiments of Hui et al. (2010) report drag coefficients of up to 4. Here, 371 we calculate drag coefficients of 1.54 and 1.24 for the defoliated and foliated states 372 respectively, exceeding the typically assumed value of 1. An inverse trend between 373 drag force and drag coefficient is surprising given the drag coefficient in the 374 defoliated case is higher, when the drag force is an order of magnitude lower than 375 the foliated case. This discrepancy can be explained by morphological differences. 376 Namely, the dominance of individual branches in the defoliated state, compared to 377 the dominance of a single leaf body of the foliated state, where sheltering effects 378 reduce the imposed resistance on the downstream end of the plant. 379

380 **Discussion and potential applications:**

Analysis of downstream velocity, turbulent kinetic energy and pressure field 381 simulations have demonstrated the importance of explicitly representing the 382 morphological complexity of plants in the numerical description of flow in vegetated 383 channels. The vertical and lateral distribution of the plant morphology is shown to 384 form canopy shear layer turbulence, likely to be dominated by Kelvin-Helmholtz and 385 Görtler-type vortices, which evolve downstream of the plant (Ghisalberti and Nepf, 386 2002). The approach provides a high resolution, spatially distributed set of modelled 387 hydraulic data which can provide the framework for evaluating turbulence-388 389 vegetation-energy loss relationships, and in particularly a means for calculating drag coefficients for individual plant species. 390

The ability to incorporate morphologically complex vegetation into a numerical 391 scheme has major implications for the modelling of flow, sediment transport and the 392 393 associated evolution of vegetated and partially-vegetated near surface landscapes. When modelling flow, the approach better allows us to understand the flow 394 disturbance introduced by vegetation, providing a full flow field simulation of the 395 three-dimensional velocity and pressure fields. This extends beyond the work of 396 Manners et al. (2013), who used a vertically averaged two-dimensional model 397 around stands of *Tamarix spp*. We show that the vertical and lateral position of the 398 vegetation, specifically the distribution of the main body of the foliage, results in a 399 complex velocity field, and this directly influences the shape of the vertical velocity 400 401 profile. Therefore across different species, it is likely that the distribution of foliage will be significant in controlling the flow patterns observed. For shrubs with an open 402 area beneath the primary leaf mass, Freeman et al. (2000) demonstrated that flow is 403 404 significantly diverted beneath the canopy, with an acceleration of the sub-canopy

flow. Similar velocity profiles were noted in field studies of flow around natural 405 willows by Bölscher et al. (2005). In this paper we have successfully modelled 406 similar velocity profiles (Figure 5), and this sub-canopy flow component will have 407 408 direct implications for elevated bed shear stresses around the plant and for surface scour. When modelling flow around woody vegetation types, consisting of both a 409 branch and foliage component, there is a clear need to accurately represent this 410 morphological complexity. An over-simplified representation (e.g. a simple cylinder) 411 would fail to capture the full complexity of flow field, omitting key features such as the 412 sub-canopy flow, as well as the structure of wake shape. Järvelä et al. (2006) 413 specify that for predicting erosion and sediment transport, a three-dimensional 414 modelling solution that can adequately model the turbulent flow field is needed. Our 415 416 approach meets these demands, and therefore has potential for modelling sediment transport dynamics. Crucially, we are developing the method to include a digital 417 elevation representation of the bed, which is coupled to a sediment routing model, 418 419 thereby offering the ability to model vegetation-flow-sediment interactions simultaneously. This development will allow sediment particles to be tracked around 420 vegetation, and the patterns of local scour and deposition to be mapped. 421

However, the results presented here describe only a static representation of a single 422 plant morphology. Aquatic vegetation is seldom found in isolation (Sand-Jensen and 423 Madsen, 1992), and as such the forces on individual plants can be reduced due to 424 sheltering and through the reduced velocities in wakes from upstream plants. 425 Furthermore, flow forcing will cause foliage reconfiguration through streamlining, 426 which will subsequently reduce the drag. This has been shown to be more important 427 in drag reduction than stem bending and enables plant survival through either static 428 or dynamic reconfiguration (Nikora, 2010; Usherwood et al., 1997). These 429

430 reconfiguration processes occur over a range of spatial scales from individual leaves to entire plant-patches (Albayrak et al., 2013; Sand-Jensen, 2003), and therefore an 431 explicit representation of changes to plant posture through time is also essential. 432 433 Work is therefore currently underway to develop a dynamic approach that accounts for multiple dynamic, morphologically complex plants, incorporating reconfiguration 434 and subsequent form drag reduction by developing further the approach of 435 Marjoribanks et al. (2014c). This involves applying a time-varying biomechanical 436 model coupled with Large Eddy Simulation (LES) to predict plant motion through 437 438 time.

Recent experimental work has shown how the interaction of neighbouring emergent 439 vegetation patches can influence deposition dynamics (Meire *et al.*, 2014). This has 440 been extended into a numerical scheme, where de Lima et al. (2015) used CFD to 441 442 show that patch distributions and interactions may be responsible for the feedbacks that influence the evolution of vegetated landscapes at the channel scale. However, 443 in both examples vegetation is represented by cylinders of varying densities. 444 Developing an approach which includes multiple, dynamic representations of 445 morphologically complex plants derived from TLS will allow sediment dynamics to be 446 further explored. Furthermore, the approach we propose is not limited to woody 447 species associated with riverine settings, it is possible to apply the methodology to a 448 vegetated estuarine environment where sediment dynamics are of critical 449 importance. 450

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Figures:









Figure 2: Stages of the voxelisation process, for the foliated (a-c) and defoliated (d-f) subsections: (a and d) illustrate the post-processed point cloud; (b and e) the userdefined octree structure with a cell size of 0.01 m fitted around the point cloud; and (c and f) the voxelised representation, following extraction of *XYZ* coordinates of octree centroids.



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Figure 3: Downstream (*u*-) velocity field data for the defoliated state: (a) slices at 0.4 and 0.6 *Z/h*. The position of the plant is marked as the solid black region. Downstream wakes can coalesce or act independently from one another, based on the separation distance of individual branches. (b) Vertical slice taken at the midline (0.5 *Y/w*), where a spatially non-uniform wake shape in the vertical dimension is shown. The wake zone at 0.2-0.4 *Z/h* is associated with the main branching point, and extends ≈7 plant lengths downstream.



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Figure 4: Downstream (u-) velocity field data for the foliated state: (a) slices at 0.4 482 and 0.6 Z/h show a single, more pronounced zone of flow separation and 483 reattachment, indicative of behaviour shown by a bluff object. (b) Vertical slice taken 484 at the midline (0.5 Y/w) illustrates two discrete wakes. Similarly to the defoliated 485 case, the lower wake corresponds with the branching point at 0.2-0.4 Z/h although 486 only extends ≈3 plant lengths downstream. Above this, a more pronounced wake at 487 0.45-0.65 Z/h corresponds with the bulk of the leafy blockage, extending ≈ 7 plant 488 The leafy component has a first order control on the lengths downstream. 489 production of a spatially heterogeneous velocity field. 490





Figure 5: Vertical velocity profiles extracted from the midline (0.5 Y/w) at increasing 493 distances downstream: (a) 0.25 X/l, (b) 0.30 X/l, (c) 0.40 X/l. The inset graph in (a) 494 495 illustrates an idealised inflected velocity profile often used to characterise vegetated flows. The velocity profiles illustrate the complex vertical structure in the wake of the 496 flow. Three velocity zones are identified, namely: a zone of relative flow acceleration 497 beneath the bulk of the plant in the near bed region (sub-canopy flow), a zone of flow 498 acceleration above the plant in the free stream zone, and between these, a non-499 500 uniform low velocity zone associated with flow deceleration due to the bulk of the plant blockage. The magnitude and size of the low velocity zone is exaggerated in 501 the foliated state, where the leaf body acts to further decelerate flow in the wake. 502



Figure 6: Turbulent Kinetic Energy (TKE) for (a) defoliated and (b) foliated scenarios, 0.45 *Z/h*. In both cases, a zone of high TKE (> 0.04 m²/s²) is evident proximal to the outer edge of the vegetation. In the defoliated scenario, this is enclosed by a slightly lower zone of TKE (0.03-0.04 m²/s²), whereas in the foliated scenario, the high TKE zone is larger, and persists in the downstream direction. Overall, TKE patterns indicate a greater form drag contribution in the foliated case.



Figure 7: Pressure fields at 0.45 *Z/h* for: (a) the defoliated state, where individual branches cause the formation of isolated zones of high pressure upstream, and low pressure downstream. (b) The foliated state exhibits different behaviour, with the formation of a more pronounced zone of high pressure upstream, and coalescence of the low pressure zone downstream; again indicative of bluff behaviour.

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