

SUPERCAL: CROSS-CALIBRATION OF MULTIPLE PHOTOMETRIC SYSTEMS TO IMPROVE COSMOLOGICAL MEASUREMENTS WITH TYPE Ia SUPERNOVAE

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ABSTRACT

Current cosmological analyses, which use Type Ia supernova observations, combine supernova (SN) samples to expand the redshift range beyond that of a single sample and increase the overall sample size. The inhomogeneous photometric calibration between different SN samples is one of the largest systematic uncertainties of the cosmological parameter estimation. To place these different samples on a single system, analyses currently use observations of a small sample of very bright flux standards on the *Hubble Space Telescope* system. We propose a complementary method, called “Supercal,” in which we use measurements of secondary standards in each system, compare these to measurements of the same stars in the Pan-STARRS1 (PS1) system, and determine the offsets for each system relative to PS1, placing all SN observations on a single, consistent photometric system. PS1 has observed 3π of the sky and has a relative calibration of better than 5 mmag (for $\sim 15 < griz < 21$ mag), making it an ideal reference system. We use this process to recalibrate optical observations taken by the following SN samples: PS1, Supernova Legacy Survey, SDSS, CSP, and CfA1-4. We measure discrepancies on average of 10 mmag, but up to 35 mmag, in various optical passbands. We find that correcting for these differences changes the recovered values for the dark energy equation of state parameter, w , by an average of 2.6%. This change is roughly half the size of current statistical constraints on w . The size of this effect strongly depends on the error in the $B - V$ calibration of the low- z surveys. The Supercal method will allow future analyses to tie past samples to the best calibrated sample.

Key words: dark energy – supernovae: general – surveys

1. INTRODUCTION

Since the initial discovery of cosmic accelerating expansion (Riess et al. 1998; Perlmutter et al. 1999), many samples of Type Ia supernovae (SN Ia) have been acquired to better constrain the dark energy equation of state parameter, w . As the systematic uncertainties in joint samples are nearly equal to the statistical uncertainties, increasing effort must be expended on reducing systematic uncertainties so that the total uncertainties do not hit a systematic floor. Of all the systematic uncertainties, recent analyses (e.g., Betoule et al. 2014; Scolnic et al. 2014a [hereafter S14]) found that those related to photometric calibration make up $>70\%$ of the total systematic uncertainty and pose the most immediate challenge.

Most supernova (SN) analyses that attempt to constrain w combine publicly available SN samples to improve statistics and cover a wider redshift range. To reproduce the most recent cosmological results (Betoule et al. 2014; Rest et al. 2014), one must combine SN from >10 independently calibrated photometric systems. The calibration of each system is performed by multiple groups using sometimes significantly different methodology. To date, no cosmology analysis with SN Ia has found a solution that keeps the calibration of all the various systems

consistent. Without doing so, an SN analysis likely underestimates the systematic uncertainties of the cosmological parameters. Betoule et al. (2014) showed that there are differences of 5% between the average distances of a single sample relative to the expected distances from the Λ CDM model. It is imperative to determine whether the small deviations are due to noise, calibration uncertainties, or deviations from the Λ CDM model.

In this analysis we take advantage of the uniform calibration of the Pan-STARRS1 (PS1) survey with $<1\%$ precision and accuracy (Schlafly et al. 2012) in order to measure and improve the consistency of catalog photometry between different surveys. We use publicly available data from *Hubble Space Telescope* (HST), Sloan Digital Sky Survey (SDSS), Supernova Legacy Survey (SNLS), Carnegie Supernova Project (CSP), and CfA surveys. In Section 2, we discuss how each sample is currently calibrated. We introduce an analysis of the cross-calibration between multiple systems in Section 3. In Section 4, we discuss the magnitude of the discrepancies and the implications of correcting for these, including effects on SN Ia distances and recovered cosmology. We also quantify the dominant uncertainties in this approach. Our discussion and conclusions are in Sections 5 and 6.

2. CURRENT CALIBRATION

In recent cosmological analyses, the calibration of each system may be compared directly or indirectly to the AB system (Oke & Gunn 1983; Fukugita et al. 1996). In the AB system, a monochromatic magnitude is defined such that

$$m_{\text{AB}}(\nu) = -2.5 \log_{10} \left(\frac{f_{\nu}}{1 \text{ Jy}} \right) + 8.90 \text{ mag}, \quad (1)$$

where f_{ν} is the flux per unit frequency from an object in Jy. Therefore, a magnitude 0 object should have the same counts as a source of $f_{\nu} = 3631 \text{ Jy}$.

We can define an AB *broadband* magnitude by the following equation:

$$m_{\text{AB}} = 2.5 \times \log_{10} \frac{\int (h\nu)^{-1} p(\nu) f_{\nu} d\nu}{\int (h\nu)^{-1} p(\nu) 3631 \text{ Jy} d\nu} \quad (2)$$

where $p(\nu)$ is the filter response function. This equation assumes that the detector is a photon-counting device.

Some of the surveys analyzed here calibrate their photometry to the AB system while others use Vega-calibrated systems. In either case, an AB offset can be given to convert the zeropoint of the calibration of one measured system to the true AB system. For a given system S and passband p , this may be expressed as

$$m_{\text{AB}}^{S,p} = m_{\text{Sys}}^{S,p} + \Delta_{\text{AB}}^{S,p} \quad (3)$$

where $m_{\text{Sys}}^{S,p}$ is the system magnitude, $m_{\text{AB}}^{S,p}$ is the AB magnitude, and $\Delta_{\text{AB}}^{S,p}$ is the offset for a particular filter between the system magnitude and the AB magnitude.

Using Equation (2), these offsets can be found explicitly if given a spectrum f_{ν} defined to be on the AB system, a measured passband p_{ν} , and the observed magnitude of the star in system S . For all systems below, the spectra used for this process are taken with *HST* Calspec standards (Bohlin 1996). These spectra are composite spectra from STIS and NICMOS observations and have an uncertainty of $\sim 5 \text{ mmag}$ for every 5000 \AA (Bohlin & Hartig 2002) from 3000 to 15000 \AA .

There are two major components to the systematic uncertainties of each system’s calibration: how well observations are tied to fundamental photometric standards and how well the photometric standards themselves are calibrated. The advantage of the calibration method for each survey discussed in the following is that it relies on observations of known *HST* Calspec standards for which we have accurate spectra and can compare synthetic photometry with observational photometry. The disadvantage of this approach is that the Calspec standards are sparse (~ 20 over the observable sky) and typically much brighter ($r < 13 \text{ mag}$) than normal survey stars ($r > 15 \text{ mag}$). Furthermore, different surveys use different Calspec standards.

Below, we briefly review the calibration of each of the photometric catalogs used in this analysis. We only analyze publicly available sources. A summary of the filters, calibration standards, and systematic uncertainties of each system is given in Table 1. The systematic uncertainties for each system are described such that there is an uncertainty in the common zeropoint to observations of a given filter and an uncertainty in the mean wavelength of that filter. The transmission functions of every filter from the various systems analyzed are shown in Figure 1.

This section is separated into an explanation of the calibration of the PS1 photometric system, the systems of the other higher- z surveys, and systems of the low- z surveys. The PS1, SNLS, and SDSS systems share a common calibration path, in that multiple Calspec standards are used to define the photometry on the AB system and nightly photometry can be tied directly to stellar catalogs in each survey’s natural system. The low- z systems are partly tied to the Vega system and partly tied to the AB system; only BD+17°4708 (hereafter BD+17) is used to tie magnitudes from each filter to the AB system. The AB offsets for all surveys are given in Table 1. These offsets are the same as those applied when fitting light curves of the SN.

For the low- z surveys, zeropoints of the nightly photometry are determined either by transforming Landolt (Landolt & Uomoto 2007) and Smith standards (Smith et al. 2002) onto the respective natural systems, or by transforming the nightly photometry onto the system of Landolt standards. The systematic uncertainties of the zeropoints given in Table 1 should therefore include uncertainties in the AB magnitudes of the primary standard(s) used, uncertainties in the measurements of the primary standard(s) by each survey, uncertainties in the transfer of zeropoints between the local standards to the primary standards, and systematic uncertainties in the measurements of the local standards.

2.1. Calibration of the PS1 Full Sky Sample

PS1—The PS1 photometric calibration is presented in Tonry et al. (2012b), hereafter T12. PS1 is a 1.8 m telescope on Haleakala with a field of view of 7 square degrees. The observation strategy has two large parts: a 3π survey across the entire observable sky and a Medium Deep survey for 10 fields of 7 square degrees each. Both surveys observe in $g_{\text{P1}} r_{\text{P1}} i_{\text{P1}} z_{\text{P1}} y_{\text{P1}}$ (see Figure 1 for $g_{\text{P1}} r_{\text{P1}} i_{\text{P1}} z_{\text{P1}} y_{\text{P1}}$ filters used for this analysis). T12, based on work from Stubbs et al. (2010) and Tonry et al. (2012a), uses an innovative laser diode system to accurately and precisely determine the filter bandpass edges ($\sigma_{\lambda} < 7 \text{ \AA}$) and throughput curves. The flux calibration of PS1 measurements relies on an iterative process that includes work from T12 and Schlafly et al. (2012) and is augmented by S14. T12 analyzes observations of seven *HST* Calspec standards with PS1 and compares the observed magnitudes of these standards to the predicted magnitudes from synthetic photometry. T12 then finds the AB offsets (Equation (3)) so that the observed magnitudes best match the synthetic photometry, given fixed constraints from measurements on the bandpass edges and shapes.

It is necessary that photometry from all observations from the 3π survey and Medium Deep survey can be linked by a single zeropoint for each filter. To do so, Schlafly et al. (2012) uses the “Ubercal” process (Padmanabhan et al. 2008) that creates a relative calibration across the sky and directly ties the zeropoints of all photometry to the catalogs from the fields that contain the observed Calspec standards analyzed in T12. Because PS1 repeatedly observed the same regions ~ 12 times in each filter and there are overlapping regions between different pointings, all relative zeropoints can be determined simultaneously and robustly. This procedure determines the system throughput, atmospheric transparency, and large-scale detector flat field. The solution from this process includes data from both the Medium Deep fields and the 3π sky over the full survey. From Ubercal, new photometric catalogs are created

Table 1
Previously Reported Calibration Differences Between Systems

System	Filters	Standards	Stan. Observation	ZP Err (mmag)	Wave Err (nm)	AB offsets (mmag)	References
PS1	<i>griz</i>	7	PS1	[12, 12, 12, 12]	[0.7, 0.7, 0.7, 0.7]	[-23, -33, -24, -24]	T12, S14, S15
SNLS	<i>griz</i>	3	SNLS	[3, 6, 4, 8]	[0.3, 3.7, 3.1, 0.6]	[-7, -8, -13, 4.7]	B13
SDSS	<i>ugriz</i>	3	SDSS PT	[8, 4, 2, 3, 5]	[0.6, 0.6, 0.6, 0.6, 0.6]	[-, -28, -14, -27, -20]	M8, D10, B13
CfA1/2	<i>UBVRI</i>	BD+17	Landolt	[100, 15, 15, 15, 15]	[2.5, 1.2, 1.2, 2.5, 2.5]	[-, 131, 6, -168, -410]	Land
CSP	<i>ugri.BV</i>	BD+17	Smith Landolt	[23, 9, 8, 7, 8, 8]	[0.7, 0.8, 0.4, 0.2, 0.7, 0.3]	[-, 10, -4, -13, 102, 6/-7/2]	S11
CfAK	<i>ri.UBV</i>	BD+17	Smith Landolt	[25, 7, 31, 11, 7]	[0.7, 0.7, 2.5, 0.7, 0.7]	[-3, -9, -, 80, 6]	H09a
CfAS	<i>UBVRI</i>	BD+17	Landolt	[70, 11, 7, 7, 20]	[2.5, 0.7, 0.7, 0.7, 0.7]	[-, 71, 7, -179, -406]	H09a
CfA4	<i>ri.BV</i>	BD+17	Smith Landolt	[25, 7, 11, 7]	[0.7, 0.7, 0.7, 0.7]	[-3/1, -9, 80/135, 6]	H09b

Note. Summary of various systems used in this analysis. The columns are filters used for observations, standards used to determine the absolute flux zeropoints, standard observations that detail with which telescope/camera the standards were originally observed, zeropoint errors claimed by the survey, wavelength error of the filter bandpasses, AB offsets to transform from the system magnitudes to AB magnitudes, and primary reference. The standards used by SNLS and SDSS are G191B2B, GD153, and GD71. The standards used by PS1 are given in Table 2. AB offsets for the low- z systems are generally large because the system was not defined on the AB system. Multiple values for certain offsets indicate multiple periods of a survey where the filters changed.

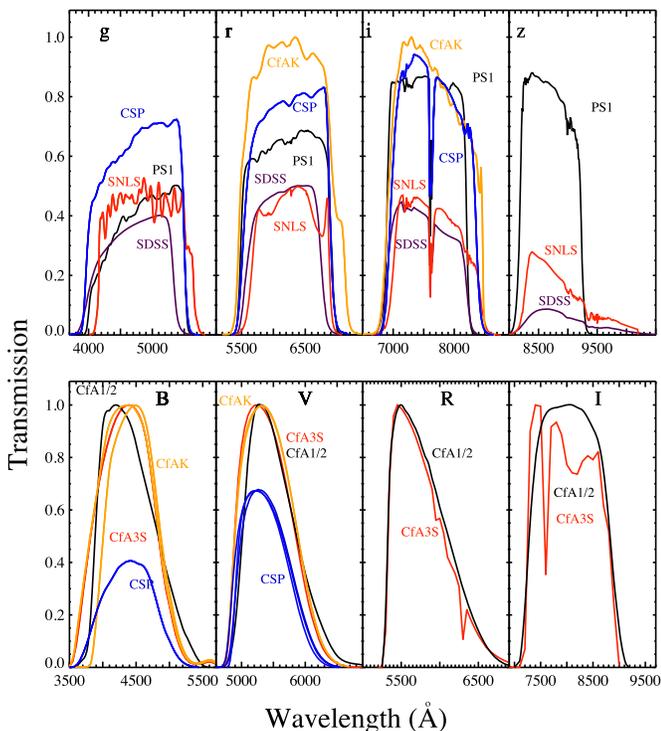


Figure 1. Filter transmission functions of all the systems in this analysis. Comparisons are broken into *griz* and *BVRI*. For both CSP and CfA-Keplercam (CfAK), multiple filters are shown because different filters were used in different periods of the survey.

across the entire observable sky with relative accuracy and precision better than 5 mmag. To improve on the initial zeropoints given by T12, S14 then iterates on this process by analyzing the entire sample of Calspec standards observed over the course of the 3π survey and redetermines the AB offsets for the PS1 system. S14 also analyzes the variation of filter transmission functions across the focal plane and finds the variations across the focal plane with a radial dependence for stars with $0.4 < g_{P1} - i_{P1} < 1.5$ to be up to 8 mmag (due to the design of the filters), although typically at a dispersion level of ~ 2 mmag. The filter throughput is measured at multiple radial

positions, and brightnesses can be corrected based on radial position on the focal plane.

For the present analysis, we repeat the process from in S14 to redetermine the AB offsets for the PS1 system. We find that the majority of the observations of the Calspec standards from T12 placed the standards at the same position on the same chip for each observation. This position was very close to the center of the focal plane, where it has been noted that there is a strong gradient in the behavior of the chip (Rest et al. 2014). The Ubercal solution for the large-scale detector flat field (Schlafly et al. 2012) at the location where these standards were observed varies by up to 20 mmag over less than a quarter of a CCD. Given this issue, observations from T12 are not included in the present analysis. In addition, only observations fainter than the saturation limit of [14.3, 14.4, 14.6, 14.1] in $g_{P1}r_{P1}i_{P1}z_{P1}$ are included. Table 2 shows both the synthetic photometry of the six Calspec standards and the Ubercal photometry of these standards. As shown in Table 3, we find that corrections from S14 of 20–35 mmag in each filter are needed. The significant size of these corrections is partly due to the update of the *HST* Calspec spectra. Further information will be given in the public release of the PS1 data.

2.2. Calibration of Intermediate and High- z Surveys

SDSS-II—The basis for the Sloan Digital Sky Survey-II (hereafter, SDSS) calibration is presented in Holtzman et al. (2008) and Doi et al. (2010), with important updates given in Betoule et al. (2013). The primary instrument of the SDSS Supernova Survey is the SDSS CCD camera (Gunn et al. 1998), which was mounted on a dedicated 2.5 m telescope (Gunn et al. 2006) at Apache Point Observatory, New Mexico. The survey observed in the five optical bands: *ugriz* (Fukugita et al. 1996; see Figure 1 for the *griz* filters used for this analysis). The survey covers a 300 square-degree region ($2^\circ 5$ wide over 8 hr in right ascension). This analysis explores photometry of the region centered on the celestial equator referred to as “Stripe 82.” The measurement of SDSS effective passbands is described in Doi et al. (2010).

The absolute flux calibration was determined using the SDSS Photometric Telescope (PT) observations of Calspec solar analog stars (Tucker et al. 2006). This process is described in detail in Holtzman et al. (2008). Betoule et al.

Table 2
PS1 Observed and Synthetic Magnitudes of Calspec Standards

Star	Filter	Obs. Magnitude	Syn. Magnitude
SF1615	g_{P1}	16.975 (0.007)	16.996
Snap-2	g_{P1}	16.413 (0.008)	16.447
Snap-1	g_{P1}	15.477 (0.007)	15.495
WD1657+343	g_{P1}	16.212 (0.007)	16.224
KF06T2	g_{P1}	14.391 (0.007)	14.429
lds749b	g_{P1}	14.562 (0.010)	14.573
C26202	g_{P1}	16.651 (0.008)	16.676
SF1615	r_{P1}	16.523 (0.007)	16.562
Snap-2	r_{P1}	16.012 (0.008)	16.046
Snap-1	r_{P1}	15.857 (0.007)	15.894
WD1657+343	r_{P1}	16.669 (0.007)	16.693
KF06T2	r_{P1}	13.573 (0.010)	13.606
lds749b	r_{P1}	14.765 (0.008)	14.808
C26202	r_{P1}	16.347 (0.007)	16.368
SF1615	i_{P1}	16.360 (0.006)	16.385
Snap-2	i_{P1}	15.878 (0.007)	15.904
Snap-1	i_{P1}	16.191 (0.007)	16.202
WD1657+343	i_{P1}	17.053 (0.006)	17.073
lds749b	i_{P1}	15.000 (0.010)	15.039
C26202	i_{P1}	16.240 (0.008)	16.263
GD153	z_{P1}	14.230 (0.007)	14.263
P177D	z_{P1}	13.137 (0.008)	13.154
SF1615	z_{P1}	16.285 (0.006)	16.318
Snap-2	z_{P1}	15.846 (0.006)	15.875
Snap-1	z_{P1}	16.393 (0.006)	16.424
WD1657+343	z_{P1}	17.346 (0.007)	17.360
KF06T2	z_{P1}	13.083 (0.010)	13.084
C26202	z_{P1}	16.211 (0.006)	16.245
GD153	y_{P1}	14.450 (0.007)	14.472
P177D	y_{P1}	13.135 (0.007)	13.135
SF1615	y_{P1}	16.269 (0.006)	16.278
Snap-2	y_{P1}	15.837 (0.007)	15.853
Snap-1	y_{P1}	16.581 (0.007)	16.567
WD1657+343	y_{P1}	17.570 (0.006)	17.579
KF06T2	y_{P1}	12.980 (0.007)	12.991
lds749b	y_{P1}	15.380 (0.008)	15.401
C26202	y_{P1}	16.225 (0.007)	16.251

Note. The calspec standard stars with adequate PS1 photometry are presented here. Both the observed and synthetic magnitudes of these standards are given before an AB correction is applied to the natural PS1 magnitudes (from Tonry et al. 2012b). The uncertainties in these measurements are given in brackets. The synthetic spectra can be found on the Calspec website (<http://www.stsci.edu/hst/observatory/crds/calspec.html>); we use version 005 in this analysis.

(2013) updated the AB offsets to reflect recent revisions to the *HST* Calspec observations and SDSS observations. Small differences between the individual filters mounted on different columns of the camera can be neglected due to the SDSS calibration strategy (Betoule et al. 2013).

SNLS—The latest calibration of the SNLS is given in Betoule et al. (2013). SNLS uses the 3.6 m CFHT atop Mauna Kea. SNLS covers the four low extinction fields of the CFHT Legacy Survey Deep component (called D1 to D4). The fields are repeatedly imaged in the four optical bands: g_M , r_M , i_M , and z_M (see Figure 1). The original i_M filter was broken in 2007 July and replaced by a slightly different i_M (denoted i_{2M}) filter in October of the same year. As i_M magnitudes are given for all SN observations published, and not i_{2M} , we exclude i_{2M} from

Table 3
PS1 Photometric System

Filter	S14 (mmag)	S15 (mmag)	S14–S15 <i>HST</i> -Recal	S14–S15 Improved Phot
g_{P1}	-8 ± 12	-20 ± 8.0	-7	-13
r_{P1}	-10 ± 12	-33 ± 8.0	-9	-24
i_{P1}	-4 ± 12	-24 ± 8.0	-9	-15
z_{P1}	-7 ± 12	-28 ± 8.0	-9	-12

Note. Corrections of the AB offsets from the original definition of the PS1 calibration as given in T12. S15 includes the updates to the most current *HST* Calspec magnitudes (version 005). The breakdown of the change in values due to the *HST* version update and from our own improved photometry is given in the last two columns, respectively. The list of Calspec standards and synthetic and observed magnitudes used for this recalibration is given in Table 2. Offsets should be subtracted from T12 calibration.

this analysis. The field of view of the MegaCam camera is $0.96 \times 0.94 \text{ deg}^2$ (Boulade et al. 2003). Measurements of the SNLS bandpasses are presented in Regnault et al. (2009).

The SNLS calibration is determined from multiple paths, including observations of *HST* Calspec standards and Landolt stars. Spatial variations of the passband response result in a variation in the brightness found for stars observed at different positions on the MegaCam focal plane (R09). In the SNLS data release, magnitudes of the stars are transformed as if they were observed at the center of the focal plane.

2.3. Calibration of Low- z Surveys

In recent SN analyses (Betoule et al. 2014; S14) the calibration of the absolute flux of the various low- z surveys is tied to measurements of the primary standard star BD+17. For filters *ugri*, the flux is calibrated to the Smith et al. (2002) magnitudes of BD+17. For filters *UBVRI*, the flux is calibrated to the Landolt magnitudes of BD+17. Magnitudes from Smith et al. (2002) are expected to be consistent with the AB system at better than 4 mmag. Landolt & Uomoto (2007) showed that the Landolt magnitudes of various standard stars and the AB magnitudes are consistent to 6 mmag.

Data from the Calan/Tololo survey (Hamuy et al. 1993) are not included in this analysis because the published number of comparison stars is quite small and a large fraction of the stars are below the -30° declination limit of the PS1 3π survey.

CSP—The basis for the CSP calibration is presented in Contreras et al. (2010). The CSP optical follow-up campaigns were carried out with the Direct CCD Camera attached to the Henrietta Swope 1 m telescope located at the Las Campanas Observatory. The survey observed in *ugriBV* and the field of view of the observations is $8'7 \times 8'7$. Definitive measurements of the CSP filter throughput curves were carried out at the telescope using a monochromator and calibrated photodiodes (Rheault et al. 2010; Stritzinger et al. 2011).

CSP SN magnitudes are published in the native photometric system, defined by the Swope filter response functions of Stritzinger et al. (2011) and the primary standard BD+17. The CSP local standard magnitudes are published in the standard system, and we convert these magnitudes onto the CSP native system using the transformation equations provided. As discussed in Stritzinger et al. (2011), we use the three different filter transmission functions for the CSP *V* band (shown in

Figure 1) for the three periods of the CSP survey in which a different filter was used (labeled “CSP₁,” “CSP₂,” “CSP₃” for this analysis).

CfA4—The basis for the CfA4 calibration is presented in Hicken et al. (2012). The CfA4 data were obtained on the 1.2 m telescope at the Fred Lawrence Whipple Observatory (FLWO), using the single-chip, four-amplifier CCD KeplerCam4. Observations were acquired in a field of view of approximately 11'5 × 11'5. C. Cramer et al. (2015, in preparation) measured the FLWO 1.2 m KeplerCam *BVr'i'* passbands using the monochromatic illumination technique initially described in Stubbs & Tonry (2006). No atmospheric component is included in the KeplerCam filter transmission curves. As discussed in Hicken et al. (2012), the 1.2 m primary mirror deteriorated during the course of the CfA4 so that different transmission functions for various filters were recognized for different parts of the survey (labeled “CfA4_1” and “CfA4_2” in this analysis).

CfA3—The basis for the CfA3 calibration is presented in Hicken et al. (2009). The CfA3 sample was acquired on the F. L. Whipple Observatory 1.2 m telescope, primarily using two cameras: the 4Shooter camera and KeplerCam. The field of view of the observations was approximately 11'5 × 11'5. *UBVRI* filters were used on the 4Shooter (hereafter, CfAS), while *UBVr'i'* filters were used on KeplerCam (hereafter, CfAK). The 4Shooter *BVRI* passbands are given in Jha et al. (2006). The KeplerCam *UBVr'i'* are measured in C. Cramer et al. (2015, in preparation), as discussed in the CfA4 subsection above.

CfA2—The basis for the CfA2 calibration is presented in Jha et al. (2006). The CfA2 sample was acquired on the F.L. Whipple Observatory 1.2 m telescope, with either the Andy-Cam CCD camera or the 4Shooter camera. Similar to CfA3, the field of view was 11'5 × 11'5. *UBVRI* filters were used on both cameras.

CfA1—The basis for the CfA1 calibration is presented in Riess et al. (1999). Like, CfA2, the CfA1 sample was acquired on the F.L. Whipple Observatory 1.2 m telescope, which has a field of view of 11'5 × 11'5. *BVRI* filters were used for all observations. To include this sample in our analysis, we created our own catalogs of the stellar photometry presented by matching the catalogs given in the paper to the finding charts in the paper.

3. CROSS CALIBRATION

Here we present a new calibration path: to directly tie all photometry catalogs to the homogeneous PS1-Ubercal catalog. The PS1 catalog covers 3π of the sky with ~5 mmag relative calibration, and depth to ~22 mag. In our new method, we compare the observed color differences of stars that are common to surveys with the synthetic transformations between the systems. We then correct for these differences so that all samples are calibrated in a consistent manner. The advantage of this new method is that it provides much better statistics because we can use many of the stars in the catalogs that are directly used to determine zeropoints of the SN photometry.

For a given star in which photometry is measured by two surveys in the AB system, the expected difference in magnitude can be expressed as

$$O_{S_p^1} - O_{S_{p'}^2} = Y_{S_p^1} - Y_{S_{p'}^2} + \Delta_{S_p^1 - S_{p'}^2} \quad (4)$$

where $O_{S_p^1}$ and $O_{S_{p'}^2}$ are the observed magnitudes in passband p and p' in the two systems, $Y_{S_p^1}$ and $Y_{S_{p'}^2}$ are the synthetic magnitudes (Equations (2) and (3)) of the systems, and $\Delta_{S_p^1 - S_{p'}^2}$ is the systematic discrepancy between how the calibration systems are defined. Typically, $\Delta_{S_p^1 - S_{p'}^2}$ is assumed to be 0; the main goal of this analysis is to test this assumption. $\Delta_{S_p^1 - S_{p'}^2} \neq 0$ if there are errors in the measurements of the bandpass definitions, errors in the photometry of the star compared, errors in the synthetic spectrum of the star itself, or errors in the AB offsets (Equation (3)) given for each system. Given a number of standards with well-calibrated spectra, from Equation (2) both $\Delta_{S_p^1 - S_{p'}^2}$ and wavelength shifts to $p(\nu)$ and $p'(\nu)$ can be found by comparing the observed magnitudes of stars from two surveys.

Our new approach consists of finding the differences of the observed magnitudes of the same stars observed by two surveys, and comparing these differences with the expected differences from known passband definitions and a stellar library of synthetic spectra. To do so, we fit a line to both the observed differences $O_{S_p^1} - O_{S_{p'}^2}$ of the two systems with color and the expected synthetic differences $Y_{S_p^1} - Y_{S_{p'}^2}$ of the two systems with color:

$$O_{S_p^1} - O_{S_{p'}^2} = \alpha_O (O_{S_p^1} - O_{S_{p'}^2} - c_0) + \beta_O \quad (5)$$

$$Y_{S_p^1} - Y_{S_{p'}^2} = \alpha_Y (Y_{S_p^1} - Y_{S_{p'}^2} - c_0) + \beta_Y \quad (6)$$

where O and Y describe the vector of observed and synthetic magnitudes of all overlapping stars between two surveys (input values), α and β are the linear component of the fit to the differences between the magnitudes for the observed and synthetic sequences (fitted values), and c_0 is a reference color that is chosen. The linear fit is performed versus a transformation color ($O_{S_p^1} - O_{S_{p'}^2}$ or $Y_{S_p^1} - Y_{S_{p'}^2}$) because we expect differences in magnitude between surveys with similar passbands to depend on color. If the passband shapes and edges are accurate but there is still a discrepancy in the zeropoints, then $\beta_O - \beta_Y = \Delta_{S_p^1 - S_{p'}^2}$ at the reference color, c_0 . If the passband shapes and edges of either system are incorrect, then we expect $\alpha_O - \alpha_Y \neq 0$. It is possible that $\alpha_O = \alpha_Y$ or $\beta_O = \beta_Y$ if systems are consistently wrong, although this scenario is unlikely.

To compare photometry from two different surveys, we follow a seven-step process to determine a single mean offset between the catalogs.

1. Match the astrometric positions of stars observed by two surveys to <1 arcsec. This ensures that stars will not be mismatched. To avoid potential errors related to blending, only isolated stars, those with no other star with $m < 22$ mag within a 15 arcsec radius, are included in the sample.
2. For a given band (e.g., p), or bands from different systems that are near each other in wavelength space, subtract the observed magnitudes from the two matched catalogs ($O_{S_p^1} - O_{S_{p'}^2}$). In addition, determine the transformation color to use ($O_{S_p^1} - O_{S_{p'}^2}$) where p and p' are two passbands chosen to provide the strongest and most

linear leverage on the color tilt of the magnitude differences.

3. For the chosen bands, integrate the spectral library through the passbands of both systems to determine the synthetic magnitudes in those passbands. For these library spectra, subtract the synthetic magnitudes to determine $(Y_{S_p^1} - Y_{S_p^2})$. Similarly, find the color $(Y_{S_p^1} - Y_{S_p^2})$.
4. For the observed sequence of stars, adopt a magnitude cut to reduce the Malmquist bias from the PS1 faint stars included in the sample. No magnitude cut is determined from the other samples because all catalog stars are used in the external analyses to determine the calibration of the SN photometry. We also adopt a bright-end cut for PS1 magnitudes of [14.8, 14.9, 15.1, 14.6] in $g_{P1}r_{P1}i_{P1}z_{P1}$ because of concerns about linearity brighter than these magnitudes (Schlafly et al. 2012).¹²
5. For the observed sequence of stars, correct the stellar magnitudes for Milky Way reddening using the known positions of the stars and extinction values from Schlafly & Finkbeiner (2011) with a 2D sky map. The extinction values are specific to each system.
6. Choose a specific color range (e.g., $g-i$) of the catalog stars used in the analysis to reflect the same colors of the stars in the synthetic library.
7. Fit α_O , β_O and α_Y , and β_Y to the observed and synthetic sequences, respectively. All photometric errors are propagated and we perform iterative 3- σ clippings to determine best-fit values.

An illustration of these steps is shown in Figure 2. The offset $\Delta_{S_p^1 - S_p^2}$ is determined from comparing the differences in β at a reference color c_0 of the fitted lines to the synthetic and observed differences. The statistical errors in either case include both the error in the measurement of the linear fit to the observed and synthetic distributions. We check the dependence of the offset on both brightness and R.A., but only make a cut on brightness to prevent a Malmquist bias. We do not correct for a spatial bias from any survey within this analysis, although this can be done in future analyses.

4. RESULTS

4.1. Discrepancies Between Surveys

We follow the procedure explained in the previous section to determine discrepancies between PS1 and each available catalog. For each comparison, we fit the differences between observations from two different systems but with similar passbands, and attempt to remove the dependence on color. Because the main purpose of this analysis is to more consistently tie each system to the *HST* Calspec system, we use the *HST* Calspec library as our spectral library to determine the color transformation between the two systems. All Calspec standards used in this analysis have a relatively small color range of $0.35 < g-i < 0.55$ mag. Because we do not extrapolate beyond this color range, the number of stars used in the comparison is limited. This is further discussed in Section 4.2.

For the higher- z surveys, we use $g_{P1}-i_{P1}$ for the transformation color for these comparisons because this choice results in the smallest scatter in residuals. Other choices for the

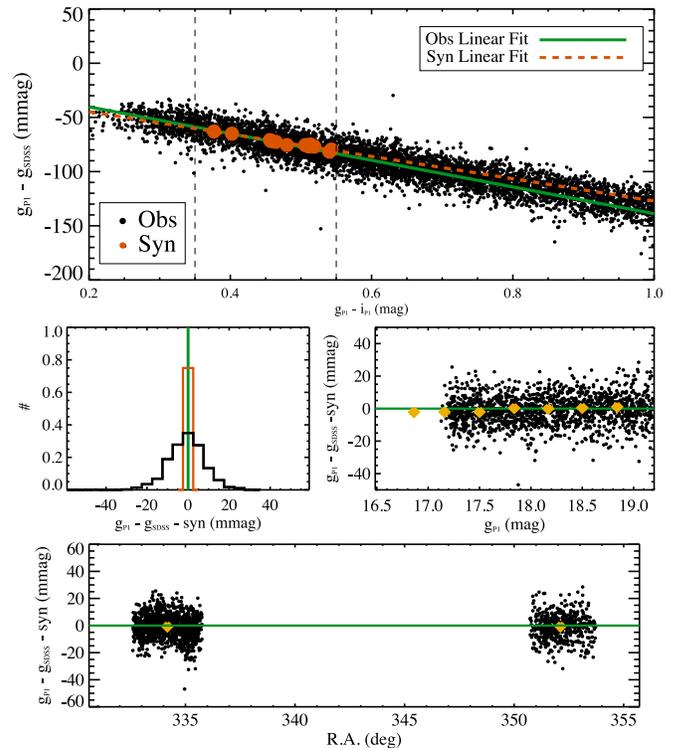


Figure 2. Visual representation of the steps of the Supercal method. The top panel shows the synthetic and observed differences in brightness of stars observed with the g_{SDSS} and g_{P1} band. Observed stars are shown in black and synthetic stars are shown in red. A linear transformation is fit to both the synthetic and observed trend. In the middle-left, a histogram is shown of the residuals from subtracting the synthetic trend from the observed stellar photometry. The histograms are normalized to unity. The residuals as a function of magnitude are given in the middle-right. The bottom panel shows the dependency of the residuals on sky position (bins given as yellow triangles).

transformation color produce similar results, but with larger uncertainties. Additionally, using $g_{P1}-i_{P1}$ rather than a color from another survey's observations allows us to keep our comparisons consistent (see Figure 2). However, because of issues at blue wavelengths, including the Balmer jump, we use the transformation color $B-i$ to compare g_{P1} to the B band. In this case, we must perform a two-dimensional minimization because of discrepancies in $B-g_{P1}$ versus $B-i_{P1}$, where the B measurement comes from the comparison sample (see discussion of systematic uncertainties in Section 4.2).

We present the results from the offsets ($\Delta_{S_p^1 - S_p^2}$) found after removing the color transformation (see Figure 2) in Figure 3. Here, $\Delta_{S_p^1 - S_p^2} = \beta_O - \beta_Y$ and we analyze the very small color range of *HST* Calspec standards such that $\alpha_O - \alpha_Y$ is insignificant. Offsets with respect to $g_{P1}r_{P1}i_{P1}z_{P1}$ are shown for each filter of each system. The errors shown include systematic uncertainties that are discussed in the next section. We separate SNLS into its four deep fields; SDSS-II is separated into the two parts of Stripe82 that overlap with PS1 Medium Deep fields and one part for the entire Stripe82. The largest deviations are seen in the comparison between the g and B bands. The scatter of these offsets is around 2%-3%. The offsets relative to the r_{P1} and i_{P1} bands are generally < 10 mmag, although there appears to be a systematic offset between PS1 and other surveys in the r band. The offsets found relative to z band are slightly larger; in particular, there is a ~ 15 mmag offset between PS1 and SDSS. The errors shown in Figure 3

¹² Saturation is observed in PS1 magnitudes at [14.3, 14.4, 14.6, 14.1] in $g_{P1}r_{P1}i_{P1}z_{P1}$, and we conservatively add a half magnitude here.

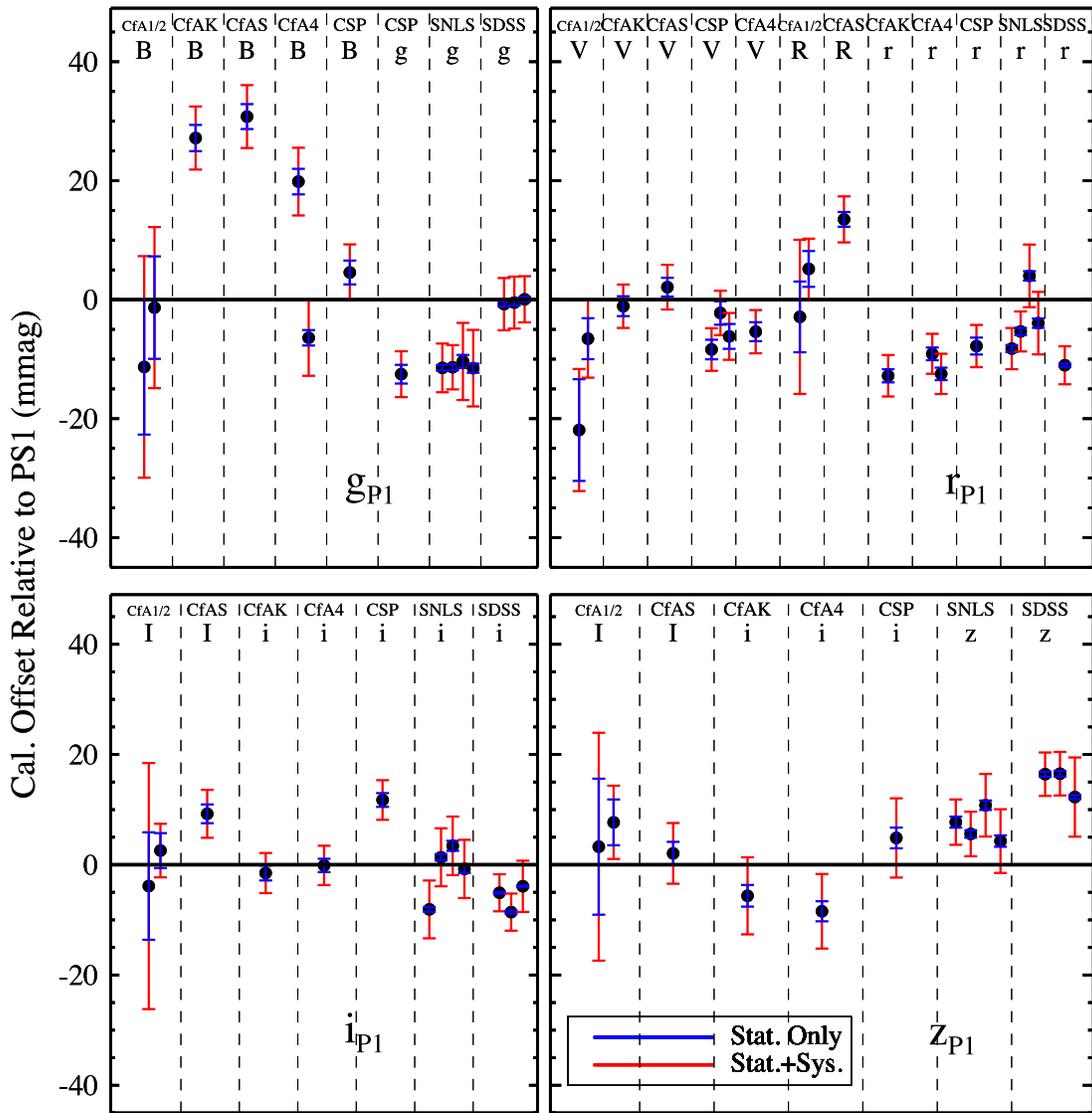


Figure 3. Deviations from agreement with the PS1 calibration for all surveys and filters. The surveys shown are CfA1, CfA2, CfAS, CfAK, CSP, CfA4, SNLS, and SDSS. The system and filter are listed for each comparison. The uncertainties shown here include both the statistical and systematic uncertainties from the Supercal process. The offsets shown here should be added to each system’s magnitudes to agree with PS1.

account for both the uncertainty from the observed magnitudes of stars as well as the uncertainty in the transformation from the synthetic magnitudes of the library standards. The uncertainties are largest for the comparison between g_{P1} and the low- z systems’ B because the most scatter is found in the transformation between these two filters, and the number of stars used for these comparisons is typically not high.

For SNLS, we are able to perform these comparisons for each of the deep fields independently and find scatter <5 mmag, which shows both the precision of the PS1 Uberscal and the SNLS calibration. Similarly, we can verify the relative calibration of the PS1 Uberscal in comparisons with SDSS for the two Medium Deep fields that overlap with Stripe82. The largest difference between the two Medium Deep fields when comparing against SDSS is 4 mmag. Overall the difference between the SDSS and SNLS calibration is ~ 10 mmag in each band, depending on the field. This is roughly within the errors given for the joint analysis between the two surveys (Betoule et al. 2013).

In the Table 4, we present the offsets of $\beta_O - \beta_Y$ using the *HST* Calspec library at $c_0 = (g - i)_0 = 0.45$ mag, and both $\beta_O - \beta_Y$ and $\alpha_O - \alpha_Y$ when using the NGSL library and a large enough color range to measure the slopes of the color transformations. We also give the number of stars common to PS1 and each survey for each comparison. As discussed below, we cannot accurately quantify the systematic uncertainties of the measurements of the slope difference $\alpha_O - \alpha_Y$, so the information given here is solely for future study. However, we note the large magnitude of the differences in slopes for some of these comparisons. For better understanding, we convert the difference in slope to a nominal difference in the mean effective wavelength for the filter used in the given survey. Both the dependence of the slope on mean effective wavelength and the corresponding shift necessary to bring the calibration into agreement with PS1 are given. Many of these values are larger than the quoted systematic uncertainties in Table 1.

The largest discrepancies seen in the B band of the low- z systems are most likely due to the use of BD+17 as the primary

Table 4
Calibration Discrepancies with PS1

Survey	Filt1	Filt2	NStar	<i>HST</i> Off. (β)	NGSL Off. (β)	Slope _{Obs} (α)	Slope _{Syn} (α)	Slope Diff.	$\frac{d\alpha/d\lambda}{\left(\frac{\text{mmag}}{\text{mag} \times \text{nm}}\right)}$	$\Delta\lambda$
	[PS1]	[O]		(mmag)	(mmag)	(mmag mag ⁻¹)	(mmag mag ⁻¹)	(mmag mag ⁻¹)		(nm)
CfA1	<i>g</i>	<i>B</i>	31	...	-15.5 ± 18.6	-302.2 ± 54.2	-334.3 ± 9.1	32.1 ± 54.9	9.4	3.4 ± 5.8
CfA2	<i>g</i>	<i>B</i>	146	-1.3 ± 13.5	8.4 ± 13.4	-290.4 ± 9.7	-334.3 ± 9.1	43.9 ± 13.3	9.4	4.7 ± 1.4
CfA3	<i>g</i>	<i>B</i>	731	27.2 ± 5.3	30.9 ± 5.3	-317.6 ± 8.0	-315.3 ± 12.2	-2.3 ± 14.6	8.7	-0.3 ± 1.7
CfA3s	<i>g</i>	<i>B</i>	396	30.8 ± 5.3	34.5 ± 5.3	-293.3 ± 9.0	-314.3 ± 12.2	21.0 ± 15.1	9.4	2.2 ± 1.6
CfA4 ₁	<i>g</i>	<i>B</i>	855	19.8 ± 5.7	20.1 ± 5.7	-349.7 ± 10.0	-307.4 ± 23.5	-42.3 ± 25.5	8.7	-4.9 ± 2.9
CfA4 ₂	<i>g</i>	<i>B</i>	912	-6.4 ± 6.4	-5.2 ± 6.4	-315.1 ± 9.3	-247.9 ± 14.1	-67.2 ± 16.9	9.3	-7.2 ± 1.8
CSP1	<i>g</i>	<i>B</i>	251	4.6 ± 4.7	1.4 ± 4.7	-321.7 ± 12.5	-299.2 ± 20.7	-22.5 ± 24.2	12.8	-1.8 ± 1.9
CSP1	<i>g</i>	<i>g</i>	362	-12.5 ± 3.9	-11.9 ± 3.8	-91.8 ± 10.8	-64.5 ± 3.2	-27.4 ± 11.2	5.8	-4.7 ± 1.9
SNLS0	<i>g</i>	<i>g</i>	200	-11.5 ± 4.1	-17.9 ± 4.1	8.2 ± 5.3	18.0 ± 1.3	-9.8 ± 5.4	8.0	-1.2 ± 0.7
SNLS1	<i>g</i>	<i>g</i>	272	-11.4 ± 3.7	-16.8 ± 3.7	18.0 ± 6.4	18.0 ± 1.3	-0.1 ± 6.5	8.0	-0.0 ± 0.8
SNLS2	<i>g</i>	<i>g</i>	264	-10.4 ± 6.5	-14.7 ± 6.5	14.4 ± 6.4	18.0 ± 1.3	-3.6 ± 6.5	8.0	-0.4 ± 0.8
SNLS3	<i>g</i>	<i>g</i>	568	-11.5 ± 6.4	-19.5 ± 6.4	12.5 ± 5.4	18.0 ± 1.3	-5.5 ± 5.5	8.0	-0.7 ± 0.7
SDSS0	<i>g</i>	<i>g</i>	3300	-0.8 ± 4.4	-0.6 ± 4.4	-115.8 ± 1.1	-121.3 ± 4.6	5.5 ± 4.7	8.7	0.6 ± 0.5
SDSS1	<i>g</i>	<i>g</i>	1525	-0.5 ± 4.4	-1.4 ± 4.4	-117.5 ± 1.5	-121.3 ± 4.6	3.8 ± 4.9	8.7	0.4 ± 0.6
CfA1	<i>r</i>	<i>V</i>	22	...	-24.4 ± 10.3	-325.9 ± 46.1	-314.8 ± 3.8	-11.1 ± 46.3	5.4	-2.1 ± 8.6
CfA2	<i>r</i>	<i>V</i>	120	-6.6 ± 6.6	-11.4 ± 6.4	-364.9 ± 14.8	-314.8 ± 3.8	-50.1 ± 15.3	5.4	-9.3 ± 2.8
CfA3	<i>r</i>	<i>V</i>	634	-1.1 ± 3.6	-2.6 ± 3.6	-357.4 ± 10.8	-348.8 ± 5.9	-8.6 ± 12.3	5.1	-1.7 ± 2.4
CfA3s	<i>r</i>	<i>V</i>	339	2.1 ± 3.8	1.8 ± 3.8	-322.3 ± 16.5	-359.7 ± 6.3	37.4 ± 17.7	5.4	6.9 ± 3.3
CSP ₁	<i>r</i>	<i>V</i>	309	-8.4 ± 3.6	-12.6 ± 3.7	-393.1 ± 11.5	-362.0 ± 6.6	-31.1 ± 13.3	5.3	-5.9 ± 2.5
CSP ₂	<i>r</i>	<i>V</i>	309	-2.2 ± 3.7	-3.4 ± 3.8	-376.3 ± 11.4	-376.8 ± 6.6	0.5 ± 13.2	5.2	0.1 ± 2.6
CSP ₃	<i>r</i>	<i>V</i>	309	-6.2 ± 3.9	-9.2 ± 4.0	-395.1 ± 11.6	-380.0 ± 7.2	-15.1 ± 13.6	5.2	-2.9 ± 2.6
CfA4 ₁	<i>r</i>	<i>V</i>	1038	-5.4 ± 3.6	-4.5 ± 3.6	-355.8 ± 9.6	-348.8 ± 5.9	-7.0 ± 11.2	5.1	-1.4 ± 2.2
CfA4 ₂	<i>r</i>	<i>V</i>	1038	-5.9 ± 3.7	-5.1 ± 3.7	-355.8 ± 9.6	-346.4 ± 5.9	-9.4 ± 11.2	5.1	-1.9 ± 2.2
CfA1	<i>r</i>	<i>R</i>	19	...	-4.1 ± 13.0	177.7 ± 46.4	76.4 ± 1.9	101.3 ± 46.4	2.7	36.9 ± 16.9
CfA2	<i>r</i>	<i>R</i>	119	5.2 ± 5.1	3.6 ± 4.8	13.8 ± 20.7	76.4 ± 1.9	-62.6 ± 20.8	2.7	-22.8 ± 7.6
CfA3s	<i>r</i>	<i>R</i>	340	13.5 ± 3.9	14.8 ± 3.9	93.3 ± 16.0	79.7 ± 2.3	13.6 ± 16.2	2.7	5.0 ± 5.9
CfA3	<i>r</i>	<i>r</i>	627	-12.8 ± 3.5	-12.4 ± 3.5	6.5 ± 10.9	8.0 ± 0.4	-1.5 ± 10.9	3.1	-0.5 ± 3.5
CfA4 ₁	<i>r</i>	<i>r</i>	1035	-9.1 ± 3.4	-4.9 ± 3.3	25.1 ± 9.4	8.0 ± 0.4	17.2 ± 9.4	3.1	5.6 ± 3.1
CfA4 ₂	<i>r</i>	<i>r</i>	1035	-12.5 ± 3.4	-9.0 ± 3.4	13.5 ± 9.3	7.9 ± 0.4	5.6 ± 9.3	3.1	1.8 ± 3.0
CSP1	<i>r</i>	<i>r</i>	309	-7.8 ± 3.5	-6.4 ± 3.6	1.7 ± 10.2	9.6 ± 0.2	-7.9 ± 10.2	3.2	-2.5 ± 3.2
SNLS0	<i>r</i>	<i>r</i>	200	-8.2 ± 3.5	-7.2 ± 3.5	23.3 ± 3.2	20.6 ± 0.6	2.6 ± 3.3	3.0	0.9 ± 1.1
SNLS1	<i>r</i>	<i>r</i>	272	-5.3 ± 5.2	-4.7 ± 5.2	23.5 ± 5.7	20.6 ± 0.6	2.8 ± 5.7	3.0	0.9 ± 1.9
SNLS2	<i>r</i>	<i>r</i>	264	4.0 ± 5.3	4.0 ± 5.3	25.2 ± 6.1	20.6 ± 0.6	4.6 ± 6.2	3.0	1.5 ± 2.1
SNLS3	<i>r</i>	<i>r</i>	569	-3.9 ± 3.4	-4.3 ± 3.4	20.7 ± 5.2	20.6 ± 0.6	0.1 ± 5.2	3.0	0.0 ± 1.8
SDSS0	<i>r</i>	<i>r</i>	3300	-11.0 ± 3.2	-12.5 ± 3.2	-4.8 ± 0.9	-2.9 ± 0.7	-2.0 ± 1.1	3.3	-0.6 ± 0.3
SDSS1	<i>r</i>	<i>r</i>	1525	-9.5 ± 3.2	-10.3 ± 3.2	-5.4 ± 1.3	-2.9 ± 0.7	-2.5 ± 1.5	3.3	-0.8 ± 0.5
CfA1	<i>i</i>	<i>I</i>	19	...	-4.7 ± 22.3	138.2 ± 67.0	87.6 ± 3.8	50.6 ± 67.1	1.9	26.1 ± 34.7
CfA2	<i>i</i>	<i>I</i>	117	2.6 ± 4.9	3.0 ± 4.8	64.4 ± 25.8	87.6 ± 3.8	-23.2 ± 26.1	1.9	-12.0 ± 13.5
CfA3s	<i>i</i>	<i>I</i>	319	9.2 ± 4.4	7.9 ± 4.4	88.4 ± 18.6	78.4 ± 6.0	9.9 ± 19.6	1.9	5.1 ± 10.1
CfA3	<i>i</i>	<i>i</i>	557	-1.5 ± 3.6	-0.8 ± 3.6	3.6 ± 12.9	12.2 ± 0.7	-8.5 ± 12.9	1.9	-4.6 ± 6.9
CfA4 ₁	<i>i</i>	<i>i</i>	969	-0.1 ± 3.6	0.8 ± 3.6	17.4 ± 10.3	12.2 ± 0.7	5.2 ± 10.3	1.9	2.8 ± 5.5
CfA4 ₂	<i>i</i>	<i>i</i>	969	0.4 ± 3.6	1.4 ± 3.6	17.4 ± 10.3	12.2 ± 0.7	5.2 ± 10.3	1.9	2.8 ± 5.5
CSP ₁	<i>i</i>	<i>i</i>	306	11.7 ± 5.4	11.3 ± 5.4	11.4 ± 10.8	14.4 ± 0.9	-2.9 ± 10.8	1.8	-1.6 ± 6.0
SNLS0	<i>i</i>	<i>i</i>	200	-8.1 ± 5.2	-6.6 ± 5.3	22.6 ± 5.1	16.2 ± 1.0	6.3 ± 5.2	1.9	3.3 ± 2.7
SNLS1	<i>i</i>	<i>i</i>	272	1.4 ± 5.3	1.8 ± 5.2	23.8 ± 6.7	16.2 ± 1.0	7.6 ± 6.8	1.9	4.0 ± 3.6
SNLS2	<i>i</i>	<i>i</i>	264	3.4 ± 5.3	3.2 ± 5.3	31.4 ± 5.7	16.2 ± 1.0	15.2 ± 5.8	1.9	7.9 ± 3.0

Table 4
(Continued)

Survey	Filt1	Filt2	NStar	<i>HST</i> Off. (β)	NGSL Off. (β)	Slope _{Obs} (α)	Slope _{Syn} (α)	Slope Diff.	$\frac{d\alpha/d\lambda}{\left(\frac{\text{mmag}}{\text{mag} \times \text{nm}}\right)}$	$\Delta\lambda$
	[PS1]	[O]		(mmag)	(mmag)	(mmag mag ⁻¹)	(mmag mag ⁻¹)	(mmag mag ⁻¹)		(nm)
SNLS3	<i>i</i>	<i>i</i>	569	-0.8 ± 3.4	-1.7 ± 3.4	24.6 ± 4.4	16.2 ± 1.0	8.4 ± 4.5	1.9	4.4 ± 2.4
SDSS0	<i>i</i>	<i>i</i>	3300	-5.1 ± 3.4	-5.6 ± 3.4	-2.9 ± 1.0	-7.2 ± 0.4	4.3 ± 1.1	1.8	2.4 ± 0.6
SDSS1	<i>i</i>	<i>i</i>	1525	-8.6 ± 3.4	-9.7 ± 3.4	-4.6 ± 1.4	-7.2 ± 0.4	2.7 ± 1.4	1.8	1.5 ± 0.8
CfA1	<i>z</i>	<i>I</i>	17	...	2.4 ± 20.7	-22.3 ± 54.8	-105.1 ± 6.0	82.8 ± 55.1	1.9	42.7 ± 28.4
CfA2	<i>z</i>	<i>I</i>	116	7.7 ± 6.6	8.2 ± 6.6	-127.2 ± 21.3	-105.1 ± 6.0	-22.1 ± 22.1	1.9	-11.4 ± 11.4
CfA3s	<i>z</i>	<i>I</i>	363	2.1 ± 5.5	8.9 ± 5.5	-80.7 ± 17.3	-101.7 ± 10.3	21.1 ± 20.1	1.9	10.9 ± 10.4
CfA3	<i>z</i>	<i>i</i>	675	-5.6 ± 7.0	0.1 ± 7.0	-189.7 ± 10.5	-168.0 ± 15.5	-21.7 ± 18.7	1.9	-11.7 ± 10.0
CfA4nat1	<i>z</i>	<i>i</i>	1117	-8.4 ± 6.8	-0.5 ± 6.7	-168.7 ± 9.4	-168.0 ± 15.5	-0.7 ± 18.1	1.9	-0.4 ± 9.7
CfA4nat2	<i>z</i>	<i>i</i>	1117	-7.9 ± 6.8	0.0 ± 6.7	-168.7 ± 9.4	-168.0 ± 15.5	-0.7 ± 18.1	1.9	-0.4 ± 9.7
CSP ₁	<i>z</i>	<i>i</i>	337	4.9 ± 7.2	9.2 ± 7.2	-175.3 ± 11.2	-165.8 ± 15.4	-9.6 ± 19.0	1.8	-5.3 ± 10.6
SNLS0	<i>z</i>	<i>z</i>	158	7.7 ± 4.1	11.6 ± 4.1	30.2 ± 4.9	17.4 ± 2.0	12.8 ± 5.3	1.6	8.0 ± 3.3
SNLS1	<i>z</i>	<i>z</i>	210	5.6 ± 5.7	7.3 ± 5.7	30.4 ± 8.2	17.4 ± 2.0	13.0 ± 8.5	1.6	8.1 ± 5.3
SNLS2	<i>z</i>	<i>z</i>	264	10.8 ± 5.7	11.4 ± 5.7	40.0 ± 5.8	17.4 ± 2.0	22.6 ± 6.1	1.6	14.1 ± 3.8
SNLS3	<i>z</i>	<i>z</i>	468	4.3 ± 4.2	6.2 ± 4.2	26.6 ± 5.4	17.4 ± 2.0	9.1 ± 5.7	1.6	5.7 ± 3.6
SDSS0	<i>z</i>	<i>z</i>	3295	16.4 ± 3.9	16.6 ± 3.9	37.3 ± 1.6	27.5 ± 2.9	9.8 ± 3.3	1.6	6.3 ± 2.2
SDSS1	<i>z</i>	<i>z</i>	1525	16.5 ± 3.9	16.8 ± 4.0	35.5 ± 2.1	27.5 ± 2.9	8.0 ± 3.6	1.6	5.2 ± 2.3

Note. Offset and slope differences between each system and PS1. Columns 2 and 3 show the PS1 filter and comparison system filter. Column 4 shows the total number of overlapping stars between $0.3 < g - i < 1.0$. Column 5 shows the offset found when using the *HST* Calspec library to find a nominal calibration offset between the systems. These offsets should be added each survey's magnitudes to agree with PS1. Columns 5–10 show both the calibration offset and the difference in predicted slopes when using the NGSL library for the spectral transformation. Columns 9 and 10 show how to convert the difference in predicted and recovered slopes of the transformation to a change in the mean wavelength of the comparison filter. The offset given when using the *HST* Calspec library is for a color range of $0.35 < g - i < 0.55$, whereas the offset and slope when using the NGSL library is for the color range $0.3 < g - i < 1.0$. CfA1 values are missing due to lack of comparison stars for a small color range.

Table 5
Main Systematic Uncertainties in the Supercal Process

Systematic:	Uncertainty
Spectral Library	$0 < x < 4$ mmag
Dust	$0.5 < x < 2$ mmag
PS1 Ubcgal	$3 < x < 6$ mmag
PS1 Nonlinearity	$0 < x < 3$ mmag

Note. Top systematic uncertainties in the Supercal process. A range of uncertainties is given here, while the individual systematic uncertainty for each system/bandpass is included in the discrepancies shown in Figure 3 and given in Table 4.

calibration standard. Bohlin & Landolt (2015) show that the luminosity of this standard has varied over the last two decades by $\sim 4\%$, and using it to anchor the calibration will result in additional systematic biases. If we instead recalibrate the low- z surveys based on the Calspec standards P177D or P330E, as suggested by Bohlin & Landolt (2015), we find that the change in B magnitudes is negligible, but the change in VRI magnitudes is -30 mmag. The net result would be a consistent 30 mmag offset in every filter when comparing the low- z BVRI to the higher- z systems. Therefore it appears likely that there is indeed an error of $\Delta(B - V) = 30$ mmag in the low- z systems, and possibly an additional gray offset of a similar magnitude.

One can adjust the PS1 zeropoints such that the PS1 calibration is aligned to any other system. By doing so, we can measure the discrepancies between the recalibrated PS1 system and all other systems. For example, correcting the PS1 system to align with SNLS requires applying offsets of -12 , -6 , $+1$, $+7$ mmag from $g_{p1}/r_{p1}/i_{p1}/z_{p1}$, respectively. We can then determine the discrepancies between all other systems and the PS1+SNLS system.

We release all the data used to make each comparison online,¹³ as well as all iterations of the versions of Figure 2 for all comparisons done in this analysis. We also include all transmission functions for each systems used in this analysis online, as well as every zeropoint for each filter.

4.2. Systematic Uncertainties

The largest systematic uncertainties in this approach are the consistency of the PS1 Ubcgal, accuracy of the spectral library, reddening of the stars from dust, and PS1 linearity. A smaller systematic uncertainty is the variation of the filter functions with radial position on the focal plane; however, for both PS1 and SNLS knowledge of this variation is used to correct the magnitudes based on their radial position. For all other systems, this variation is expected to be negligible. A summary of the dominant systematic uncertainties is given in Table 5.

The systematic uncertainties from the PS1 Ubcgal are given in D. Finkbeiner et al. (2015, in preparation). By comparing the relative calibration of SDSS and PS1, Finkbeiner et al. (2015) find that for a given sky position, there are systematic uncertainties less than 9, 7, 7, 8 mmag in *griz*. These uncertainties include the systematics from both SDSS and PS1, not only PS1. A fair upper limit for the systematic uncertainty due to PS1 is roughly half of these uncertainties, 5,

4, 4, 4 mmag, which are further reduced for the PS1 Medium Deep fields due to the large number of observations of these fields and are expected to be around 3 mmag in each filter. Since most of the comparisons between PS1 and other surveys involve stars from multiple fields, we estimate the systematic uncertainty in the PS1 Ubcgal photometry to be the quadrature sum of an error floor of 3 mmag in addition to the filter-specific uncertainty (5, 4, 4, 4 mmag) divided by the square root of the number of fields.

The systematic uncertainty associated with the spectral library used for the synthetic transformations can be determined by comparing the transformations using multiple independent spectral libraries. We analyze stellar spectra from five different libraries: the *HST* Calspec library (version 005),¹⁴ the NGSL spectral library (Heap & Lindler 2007), the INGS spectral library (A. J. Pickles et al. 2015, in preparation), the “Pickles Atlas” (Pickles 1998), and the Gunn–Stryker library (Gunn & Stryker 1983). We have to make specific cuts for each library to properly alleviate systematic biases and optimize the most consistent comparisons. For the *HST* Calspec library, the NGSL library, and the INGS library, we explicitly only include solar analog stars ($-0.6 < [O/H] < 0.3$). This cut allows for the most direct comparison between the majority of main sequence stars observed and the stars from the synthetic libraries. For the *HST* Calspec library, we only include standards that have been recently calibrated with WFC3 to ensure that only the latest updates are used. Because of known flux biases with distance from slit center in the NGSL observations,¹⁵ we only include standards that were observed within 0.5 pixels of the slit center. There is significant overlap between the INGS and NGSL libraries because the INGS library uses many NGSL spectra and includes its own correction for slit-loss in the NGSL observations. We do not exclude any spectra from the Pickles library or the Gunn–Stryker library.

Examples of differences between these libraries are shown in Figure 4, where we find the synthetic transformations between PS1 and SDSS, as well as PS1 and CfAS. We only show the transformations for a color range of $0.3 < g_{p1} - i_{p1} < 1.5$ because that is the only part of the main sequence where many stars can be found and there is the smallest amount of scatter in the transformation. There is clearly less of a dependence on the spectral library for the transformation between PS1 and SDSS because the mean effective wavelengths and wavelength range of these filters are much closer. However, the dependence can be quite significant when comparing filters between PS1 and CfAS; separation between the mean effective wavelength of filters from these systems can be >200 Å.

Because we chose to use the *HST* Calspec library as our primary spectral library, we determine the systematic uncertainty in the synthetic transformation between systems by instead using the *HST* NGSL library. As the NGSL library was also acquired using *HST*, it is a useful comparison to the *HST* Calspec library. Included in the uncertainties given in Figure 3, we find discrepancies in the offsets when using these two libraries to be in the range up to 4 mmag. Differences between the *HST* Calspec library and other libraries, like the Gunn–Stryker library or the Pickles library, can be significantly larger. We are limited to using a small color range when comparing

¹⁴ Differences in absolute flux of Calspec standards between version 003 and version 005 are on the 8 mmag level.

¹⁵ More information found here: <https://archive.stsci.edu/prepds/stisngsl/>

¹³ <http://kicp.uchicago.edu/~dscolnic/supercal/>

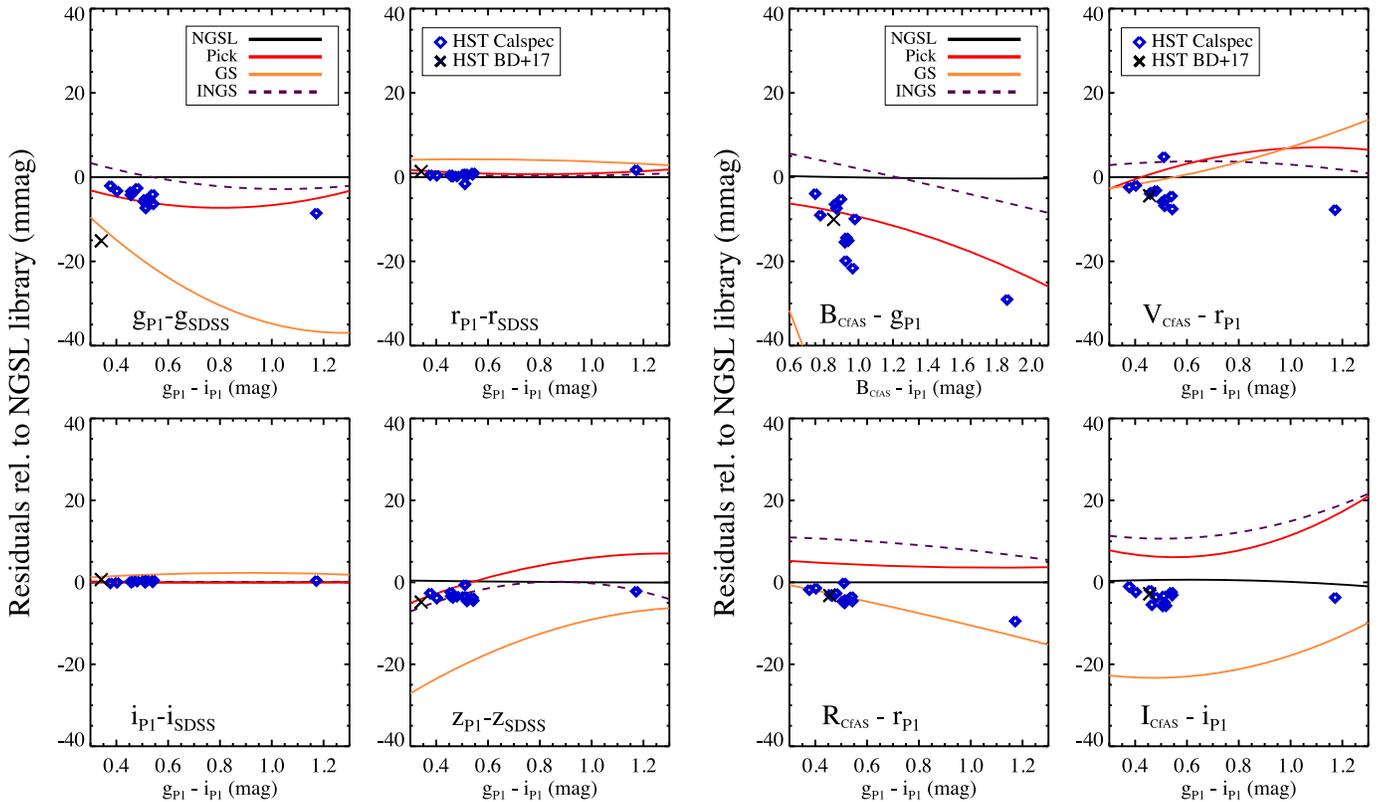


Figure 4. Left: residuals of the synthetic transformations between PS1 and SDSS when using different spectral libraries. The $g_{P1} - i_{P1}$ color is used as the transformation color for these systems. The transformation with the NGSL library is used for the baseline trend and is removed for each case. The *HST* Calspec standards are represented by points on the plots. Right: residuals of the synthetic transformations between PS1 and CfAS when using different spectral libraries. The colors $B_{CfAS} - i_{P1}$ and $g_{P1} - i_{P1}$ are used as the transformation colors for these systems.

systems due to the small amount of standards in the *HST* Calspec library. We can increase this color range by using the NGSL library to extend from $0.35 < g_{P1} - i_{P1} < 1.0$. However, because we do not have multiple *HST* Calspec standards in this larger color range, we cannot use two libraries to assess what an appropriate systematic uncertainty would be.

The impact of dust depends on whether there is a difference in the dependence on color between the dust reddening vector and temperature vector. This issue can be largely removed by accounting for the extinction in the field that each star is located in. The uncertainty in the extinction values is discussed in S14. From Schlafly & Finkbeiner (2011), we can safely assume that because the stars used in this analysis are removed from the galactic plane, all the dust represented by the MW extinction value is between us and the stars used for this analysis, and any uncertainty in this assumption is included in the total systematic uncertainty of the extinction values. We propagate the uncertainty of extinction values through the Supercal process and find that for an extinction of $E(B - V) = 0.1$ mag, we can expect systematic uncertainties of 2, 0.5, 0.5, and 1.0 mmag in *griz*, respectively.

In Figure 5 we investigate the systematic uncertainties due to nonlinearity of the PS1 stellar magnitudes. Here we remove the nominal β offset shown in Figure 3 for each survey to probe possible biases with magnitude. Overall, we choose to quantify the possible nonlinearity due to PS1 by finding the trend for each filter when comparing with SDSS. This is roughly 0, 2, 3, 5 mmag for $g_{P1}, r_{P1}, i_{P1}, z_{P1}$, respectively, over a 3 mag range from ~ 15 to 18 mag of each filter. It is unclear how much of this

nonlinearity to attribute to PS1, because comparisons with SNLS and other surveys do not appear to favor the same biases with magnitude that SDSS does. Therefore, we conservatively claim that half of this nonlinearity is due to SDSS and half to PS1. From this plot, we also see significant trends at the faint magnitudes for the low- z surveys. These trends are likely indicative of either selection biases or poor photometry of fainter stars in the low- z surveys. These biases may also affect the SN photometry, although this will require analysis in a future study.

We limit the systematic uncertainties to ones that are based on PS1 and the methodology used here, and not any of the other individual surveys. Many interesting pathologies can be found by exploring the comparisons between PS1 and other surveys. For example, there are certain fields of stars in the low- z surveys that appear to have a significantly different offsets when comparing to PS1 versus the majority of fields of these surveys. One example can be seen in the comparison between g_{P1} and g_{CSP} in Figure 6. While we find a negligible dependence of the relative offsets based on magnitude, we do see some dependence on MW dust reddening. However, this trend depends strongly on a handful of fields with high reddening, and it is unclear whether the trend is caused by the reddening or if those particular fields happen to be discrepant for other reasons. Overall we see on the order of 5–10 mmag trends with brightness, dust, or R.A./decl. for CSP as well as many of the other low- z surveys. The 5–10 mmag trends represents a rough estimate of the systematic uncertainties in these samples.

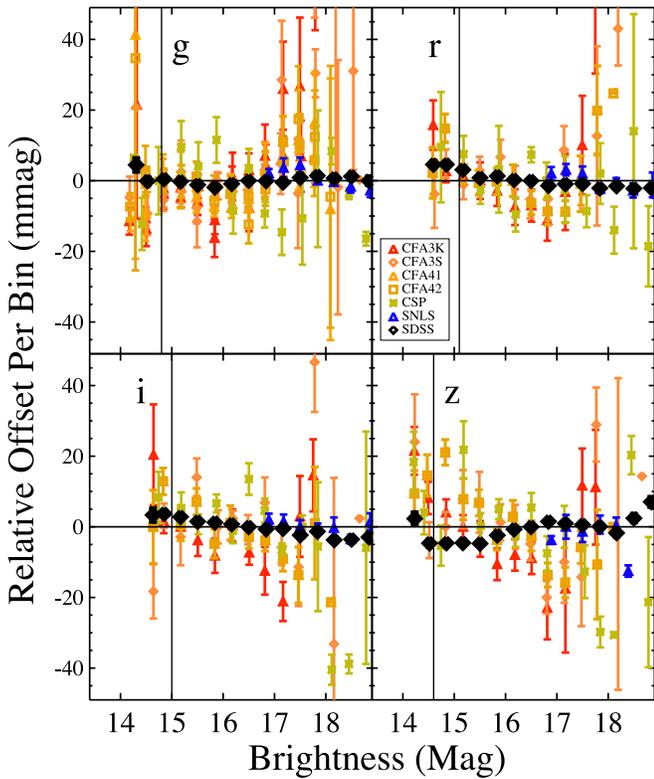


Figure 5. Relative offsets between stars in the PS1 sample and other samples as a function of apparent brightness in $g_{P1}r_{P1}i_{P1}z_{P1}$. The offsets shown are relative to the nominal Supercal correction given in Figure 3. Comparisons for each survey are shown, and in black the offsets for SDSS are highlighted to quantify potential systematic uncertainties from the PS1 nonlinearity. Vertical lines show where the PS1 sample is cut on the bright end.

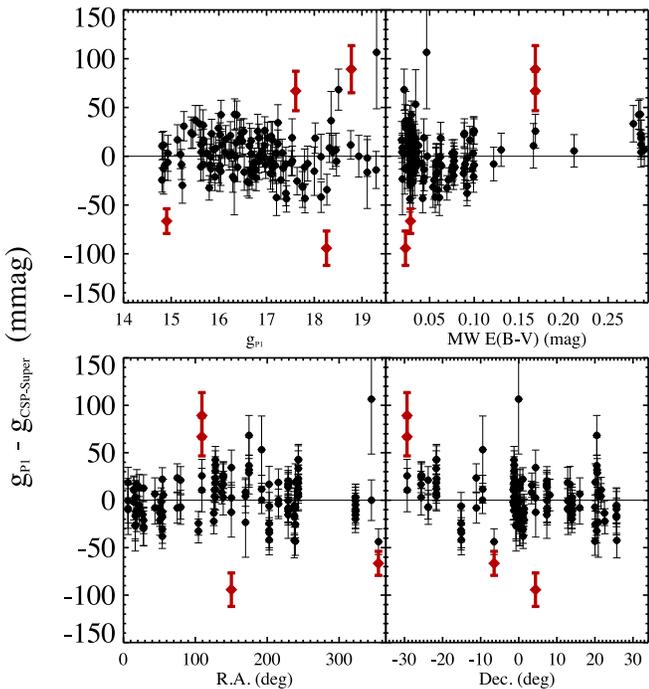


Figure 6. Relative offsets between stars in the CSP sample and PS1 as a function of apparent brightness in g_{P1} , Milky Way reddening, R.A., and decl. The offsets shown here reflect the values after the Supercal correction from Figure 3 is applied for the g_{CSP} filter. Points in red are excluded from the offset calculation as part of the iterative $3\text{-}\sigma$ clipping procedure.

4.3. Comparing SN Photometry

A more direct method to determine calibration discrepancies between various filters with the ultimate goal of consistent SN photometry would be to compare the photometry of SN observed by multiple surveys. Unfortunately, this approach is limited by both the statistics and the methodology—comparing the photometry of SN is much more difficult because the SN Ia features are relatively deep and broad relative to stellar absorption, yet narrow compared to the width of a filter. Mosher et al. (2012) compared the photometry of nine SN Ia observed by both SDSS and CSP; however, they argued that four of these SN could not be used because their cadences were either not satisfactory or the SN were not typical SN Ia, which limited the comparison. Of the remaining five SN, Mosher et al. (2012) found that the photometry of each individual SN agreed to better than 1%, although the sample scatter is up to 8% and there is no single, consistent offset for all SN. Betoule et al. (2014) performs a similar comparison to that of Mosher et al. (2012) when trying to compare CfA3 and CSP. Their sample has 17 SN, and they find offsets in $BVri$ of 5 ± 4 , -9 ± 3 , 24 ± 4 , and 3 ± 12 mmag with scatter of 42, 21, 39, and 49 mmag, respectively. No systematic uncertainties are given for this approach, and we find using Supercal that these differences are 10 ± 8 , 3 ± 9 , 4 ± 9 , and -4 ± 6 . A larger sample is needed to understand if there are errors beyond those seen in calibration, such as those due to image subtraction or astrometric registration. An alternative way to assess whether Supercal improves the consistency of these two surveys is to look at the agreement in the measured distances for the same SN using photometry from separate surveys. We find without Supercal, the difference in distances between the CSP and CfA3 surveys for 23 SN is 0.031 ± 0.026 mag; after Supercal the difference is -0.012 ± 0.026 mag. More statistics will be needed for a more robust diagnostic.

4.4. Effects on Recovered Cosmology

We may choose to remove the calibration discrepancies found between all the systems so as to create a more uniformly calibrated sample. We are able to force all systems to be relatively calibrated in a consistent manner with a given system or the average calibration from multiple systems. For the average solution we use the calibration from PS1, SNLS, and SDSS, which are the most recently calibrated systems, to determine a joint solution of the baseline-Supercal calibration. We use the offsets shown in Figure 3, and weight them by the systematic uncertainties given in Table 1. After doing so, we find average offsets from the PS1 calibration of -5 ± 3 , -7 ± 3 , -2 ± 2 , and 6 ± 4 mmag, where the uncertainties given are from the systematic uncertainties given in Table 1 combined with the uncertainties from the Supercal process.

After making the systems consistent, we can then redetermine the cosmological parameters derived from the full sample. The light curves of all SN are fit with the SNANA package (Kessler et al. 2009) so that the fits are consistent with Betoule et al. (2014); the same SALT2 model and host-mass Hubble residual step of 0.06 mag are applied. Further information about light-curve fitting, distance-bias corrections, and host masses will be discussed in the next PS1 cosmology analysis (D. Scolnic et al. 2015, in preparation). The number of SN for each system, after quality cuts explained in Betoule et al. (2014), is CfA1 (10), CfA2 (18), CfAS (33), CfAK(58),

Table 6
Differences Between the Various Surveys

Primary Calibration	Δw	$\Delta\Omega_M$
No-correction	0.000 ± 0.052	0.000 ± 0.017
Supercal-Avg	-0.026 ± 0.051	-0.005 ± 0.015
Supercal-PS1	-0.040 ± 0.055	-0.015 ± 0.015
Supercal-SDSS	$+0.010 \pm 0.052$	$+0.005 \pm 0.017$
Supercal-SNLS	-0.032 ± 0.050	-0.007 ± 0.016

Note. Differences in the recovered cosmology when calibration is forced to agree with that of a particular survey. The no-correction value is given when no change to any calibration is made. Errors given represent the total systematic error of the best-fit cosmology and include the uncertainties from the Supercal process for each filter/system.

CfA4_1 (34), CfA4_2 (9), CSP(32), SDSS (359), PS1 (111), and SNLS (235). Differences in the recovered cosmology, when including only CMB constraints from Planck Collaboration et al. (2014), are shown in Table 6 for the unaltered calibration, as well as when the calibration is forced to agree with the SDSS, SNLS, PS1, or the average calibration. The weighting of each sample is determined by the error shown in Figure 3 for each system, and we also include calibration errors from the SALT2 model, and from the *HST* AB system as part of the weighting covariance matrix. We find that values for w may change up to $\Delta w \sim -0.040$ depending on which primary calibration is used. For the average Supercal solution based on SDSS, SNLS, and PS1, the change in w is -0.026 . The primary cause of these changes is due to the uncertainty in the B and V bands, which affects the low- z SN. For the average Supercal calibration, we show the mean Hubble residual for each SN subsample in Figure 7 (top) and the difference in distances as a function of redshift when the Supercal correction is applied relative to when it is not in Figure 7 (bottom). The Supercal solution appears to significantly improve the agreement between the low- z samples and the Λ CDM model. We find mostly positive Hubble residuals from the Λ CDM model due to the host-mass correction and the distance-bias correction (for latter correction, see Figure 5 in Betoule et al. 2014; more discussion in upcoming D. Scolnic et al. 2015, in preparation). The net change in distances for each subsample is up to 0.055 mag for the low- z systems, but only 1% for the higher- z systems.

The Supercal process has a small effect on the distance scatter of the joint sample. For the entire joint sample shown in Figure 7, for each of the five cases shown in Table 6, we find a relative $\Delta\chi^2$ of [0.0, -2.3 , $+6.7$, -9.9 , $+0.3$], respectively, for 906 SN. However, if we only measure the improvement in χ^2 for the SNe with $z < 0.1$, we see a more significant improvement in each case: $\Delta\chi^2$ of [0.0, -3.2 , -10.7 , -7.2 , -11.2], respectively, for 225 SN. The effect of Supercal is obviously much larger for the low- z sample because offsets between PS1, SDSS, and SNLS are small and the calibration of SDSS and SNLS has already been connected in Betoule et al. (2013). In a full cosmology analysis, SALT2 should be retrained with the optimal Supercal solution and simulated biases of distance residuals with color should be removed (Scolnic et al. 2014b). These improvements should better show the impact of the Supercal corrections.

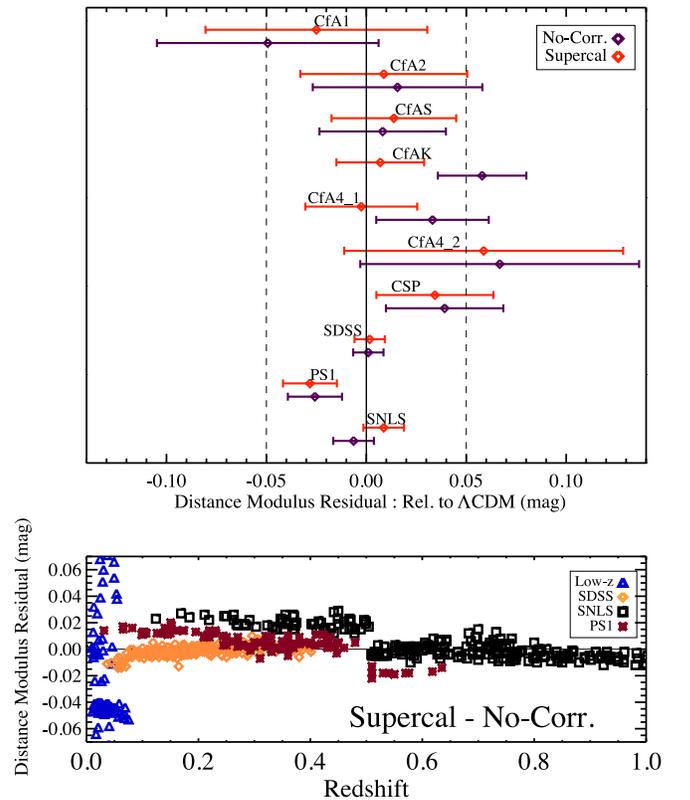


Figure 7. (Top) Mean relative Hubble residual offsets to the Λ CDM model for SN observed by each system analyzed. The points in black represent the residuals when no change to the the calibration systems are made, and in red, they represent the offsets after we apply the average Supercal correction. (Bottom) The change in distances due to forcing all calibrations to agree to the average Supercal solution. The values are such that $\Delta\mu = \mu_{\text{Supercal}} - \mu_{\text{No Corr.}}$. SN from different samples are represented by different symbols and colors, as indicated in the legend.

5. DISCUSSION

The accuracy of the Supercal technique presented in this paper depends on the number of stars common to PS1 and the comparison system, as well as the difference in effective wavelengths for the filters that are being compared. While PS1 has covered nearly the limit of its observable sky, it would still be possible to increase the PS1 statistics of bright stars by observing at shorter exposure times. This could help the absolute calibration of PS1 as well as the Supercal process. It is no longer possible for most of the other surveys analyzed here to obtain more observations of stars for other surveys, although some could work to release more of the data already acquired. A clear path to improved accuracy would be to redefine the absolute calibration of the low- z surveys on multiple standards observed by Landolt (1992), rather than BD+17. In the current scheme, the accuracy of the calibration of the low- z survey is reliant on the accuracy of the observations of BD+17 by both Landolt (1992) and *HST*. As BD+17 is a binary star, this strategy is sub-optimal.

Furthermore, a complete understanding of the impact of these relative differences between surveys can be understood only after the light-curve models are retrained with the new calibration. As the light-curve training is primarily based on low- z SN, any systematics in the calibration of these SN has an appreciable effect on the fitted SN distances.

The Supercal process is primarily used here to determine zeropoint offsets between the surveys, and does not correct for the color terms as given in Table 4. This can be done if there were more red ($g - i > 1.0$) *HST* standards, which are particularly helpful for the PS1, SDSS, and SNLS surveys, as SN at $z > 0.5$ have $g - i > 1.0$.

Instead of waiting for more observations of standard stars to be obtained by *HST*, we can apply the same Supercal process discussed above to catalogs of stars observed by *HST*. Photometry from *HST* is ideal for cross-calibration because it is most closely tied to the *HST* Calspec AB system, is photometrically stable, and is closely monitored. The difficulty is that observations taken with *HST* are typically done as part of small programs that have very different objectives, saturation limits, and selection effects. In order to bypass the various differences in the small *HST* programs, we could focus on one very large calibrated field: COSMOS (Scoville et al. 2007). Only imaging in a single band, ACS/*F814W* (roughly *i*), was obtained for the entire field, and while the relative calibration across the field is better than 3 mmag, there was no effort to define the absolute flux of the observations. This is not the case for other observations taken of the COSMOS field, so we can use other observations acquired from the Hubble Legacy Archive to determine the *HST* zeropoint of the entire field. The expected zeropoint does not differ across the sky and any change of the zeropoint with time is negligible. We find a zeropoint when calibrating to the AB system of 0.268 ± 0.003 mag, such that $F814W_{AB} = F814W_{COSMOS} - 0.268$ mag. Applying the Supercal process, we find the calibration offset relative to the PS1 of 9 ± 10 mmag with the *i*-band comparison, and 6 ± 14 mmag in the *z*-band comparison. The errors are relatively large because the *F814W* filter has a relatively different wavelength range and mean effective wavelength than that of either i_{P1} or z_{P1} . More work should be done to tie *HST* observations to PS1 so it can be included in the Supercal process.

A final question remains about the best way to use the Supercal corrections in future cosmological analyses that use SN Ia. A simplistic approach could be to not correct for any of the Supercal offsets, but instead use them as a systematic uncertainty that one could propagate into the full systematic covariance matrix. The inherent assumption of this decision is that the current calibration of each survey is optimal, given some uncertainty. This assumption certainly appears to be false. Instead, we prefer to correct for the Supercal offsets based on a weighted calibration of multiple surveys, as done for the average case in Table 4. This approach creates a homogeneous photometric calibration between the different systems and ties all the samples to the AB system. For samples that cannot be included in the Supercal analysis, due to insufficient numbers of stars or the lack of a public release of local standards, we think these samples should no longer be included in a cosmological analysis.

6. CONCLUSIONS

In this paper, we presented a new method for SN calibration. We determined the relative SN-zeropoint offsets between different filters of different systems and showed their impact on the measurement of cosmological parameters. We find that there may be systematic discrepancies between the zeropoints of 1%–2%, which propagate to up to 5% systematic errors in SN distance. This systematic error in distance can then result in

an average offset of 2%–3% in w . The primary discrepancies found are in the *B* filters of the low- z systems. More work must be done to better understand these offsets. The systematic uncertainties of this approach are shown to be of similar magnitude or greater than the statistical uncertainties, and increasing the size and color range of the spectral libraries would be one of the largest improvements to the Supercal process. Future surveys that are able to more precisely and accurately tie their calibration to the *HST* Calspec standards can use Supercal to combine their sample with past samples.

Overall, the size of the systematic uncertainty on w due to changes in the relative calibration of all surveys used is encouraging for future cosmology studies with SN Ia. While most recent SN Ia cosmology studies find that their systematic uncertainties are dominated by issues with calibration, this Supercal analysis shows that the current state may not continue much longer.

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