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2 **Experimental simulation: using generative modelling and palaeoecological**
3 **data to understand human-environment interactions**

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20 **Abstract.**

21 The amount of palaeoecological information available continues to grow rapidly, providing
22 improved descriptions of the dynamics of past ecosystems and enabling them to be seen from
23 new perspectives. At the same time, there has been concern over whether palaeoecological
24 enquiry needs to move beyond descriptive inference to a more hypothesis-focused or
25 experimental approach; however, the extent to which conventional hypothesis-driven
26 scientific frameworks can be applied to historical contexts (i.e., the past) is the subject of
27 ongoing debate. In other disciplines concerned with human-environment interactions,
28 including physical geography and archaeology, there has been growing use of generative
29 simulation models, typified by agent-based approaches. Generative modelling encourages
30 counter-factual questioning (“what if...?”), a mode of argument that is particularly important
31 in systems and time-periods, such as the Holocene and now the Anthropocene, where the
32 effects of humans and other biophysical processes are deeply intertwined. However,
33 palaeoecologically focused simulation of the dynamics of the ecosystems of the past either
34 seems to be conducted to assess the applicability of some model to the future or treats
35 humans simplistically as external forcing factors. In this review we consider how generative
36 simulation-modelling approaches could contribute to our understanding of past human-
37 environment interactions. We consider two key issues: the need for null models for
38 understanding past dynamics and the need to be able learn more from pattern-based analysis.
39 In this light, we argue that there is considerable scope for palaeoecology to benefit from
40 developments in generative models and their evaluation. We discuss the view that simulation
41 is a form of experiment and, by using case studies, consider how the many patterns available
42 to palaeoecologists can support model evaluation in a way that moves beyond simplistic
43 pattern-matching and how such models might also inform us about the data themselves and
44 the processes generating them. Our emphasis is on how generative simulation might

45 complement traditional palaeoecological methods and proxies rather than on a detailed
46 overview of the modelling methods themselves.

47

48 **Keywords:** agent-based models, pattern-oriented modelling, generative simulation models,
49 equifinality, inference

50 **Introduction**

51 Palaeoecologists are enjoying a data-rich era, with reconstructions using multiple proxies
52 across large networks of sites now common, supported by advances in computational power
53 and informatics (Brewer et al., 2012). Large amounts of palaeoecological information, such
54 as that stored in the NEOTOMA and the Global Charcoal databases, are available online and
55 can be interrogated using open-source software such as R (Blarquez et al., 2014; Goring et
56 al., 2015). Likewise, the variety of proxies available to palaeoecologists has increased
57 (Meadows, 2014), with, for example, ancient genomics providing new data and insights about
58 the ecological dynamics of the ecosystems of the past (Hofman et al., 2015; Orlando and
59 Cooper, 2014). The signatures of past changes and the processes generating them are usually
60 assumed to be present in the spatial and temporal patterns embedded in these data and given
61 the wealth of data available describing past ecosystems, palaeoecology is now awash, if not
62 drowning, in ‘patterns’ of all sorts. This wealth of data and patterns is allowing new avenues
63 for palaeoecological research. For example, there is growing interest in the use of the
64 information and knowledge gleaned from natural archives to inform understanding of
65 contemporary ecosystem-service provisioning and the resilience and threshold behaviour of
66 environmental systems, and to improve policy and practice (Jeffers et al., 2015; Pearson et
67 al., 2015).

68

69 Understanding the dynamics of feedback-driven ecological systems requires a pluralistic
70 approach; in this pursuit the description of long-term ecosystem dynamics that underpins
71 palaeoecology is a fundamental component, but is not sufficient of itself (Bowman et al.,
72 2015). Models, and the intellectual practice of process-based modelling, also have an
73 important role to play in such efforts. Computational and data advances have allowed the
74 development of detailed environmental models over increasingly finer and larger scales in

75 space and time. Computer power is not, however, a panacea for the scaling and inferential
76 challenges faced by (palaeo)ecologists, nor does it negate the fundamental issues about
77 representation that are central to all simulation. From the outset we acknowledge that models
78 will always remain open to the criticism that they are incomplete, although as both Bryson et
79 al. (2007) and Millington & Wainwright (2016) comment this incompleteness is true of all
80 explanations and theories. Furthermore, *purpose* will remain the key determinant of how
81 useful simulation might be in a given context and what form any such simulation should take;
82 in short, not all questions require an explicit formal model, even if scientists are implicitly
83 modelling all of the time. Alongside changes in computational power supporting more
84 detailed representation, modellers have moved beyond seeing simulation models solely as
85 predictive devices and have begun to emphasise their heuristic and exploratory value
86 (Oreskes et al., 1994). Importantly, there has been growing recognition that a simple
87 confrontation of model predictions with observed data (so-called ‘pattern-matching’) is
88 inadequate for model evaluation (O’Sullivan and Perry, 2013). In response, environmental
89 modellers have developed frameworks for making process-related inferences from
90 complicated simulation models that go beyond simple pattern matching (single model vs.
91 single data) and emphasise multiple hypothesis testing and the simultaneous evaluation of
92 multiple model structures (Grimm and Railsback, 2012; McIntire and Fajardo, 2009). These
93 frameworks can support the heuristic use of simulation models to explore palaeoecological
94 questions, but to date there have been limited efforts to link these important developments in
95 palaeoecological and human-environment models.

96

97 In this paper, we focus on how generative models can be used to strengthen the inferences
98 made from palaeoecological data and the patterns embedded in them. We are concerned with
99 the use of models to understand past human-environment interactions rather than the

100 technical questions of *how* to develop a simulation model. Two recent reviews of modelling
101 human-environment interactions in the Anthropocene help to fill this gap: Verburgh et al.
102 (2016) discuss, in general terms, the challenges of adequately representing human-
103 environment interaction in coupled socio-ecological systems and Barton et al. (2016) describe
104 in some detail the design and implementation of the MedLand Modeling Laboratory. Thus,
105 we do not provide an exhaustive overview of the application of simulation models to
106 palaeoecological questions (in fact the field is large enough that this is probably impossible in
107 a single review); rather, we seek to highlight how recent advances in the computational tools
108 available to ecological modellers can support better inference making from (simulation)
109 models. In particular, we consider the view that models represent an alternative mode of
110 experiment (Dowling, 1999; Peck, 2004); this is a particularly relevant argument for
111 historical sciences such as palaeoecology where direct manipulation of the system is
112 impossible. We focus on how new frameworks for model selection and evaluation offer
113 powerful frameworks within which *in silico* experimentation might be grounded and suggest
114 that palaeoecological records provide an ideal test-bed for the application of these tools.
115 Generative simulations models, including agent-based approaches, can be used to explore
116 prehistoric human-environment interactions in ways that are currently under-explored; such
117 approaches have been surprisingly little used to explore palaeoecological questions.

118

119 **Generative Modelling**

120 Many different typologies have been proposed for ecological models, including some based
121 on the underlying techniques used (e.g. mathematical vs. empirical vs. simulation) and others
122 on the motivation behind the modelling exercise (e.g. prediction vs. heurism) (Perry and
123 Millington, 2008). Gerbault et al. (2014) distinguish between ‘discriminative’ and ‘generative’
124 simulation models; the former focus on finding patterns in data without explicit consideration

125 of causality, and the latter with developing representations of system that do address the
126 underlying processes generating the patterns and structures we observe (“story testing”, *sensu*
127 Gerbault et al., 2014). Epstein (1999, 2006, 2008) has advocated for a generative approach in
128 modelling social systems, using agent-based models (ABMs) to evaluate how complex social
129 systems may be built up of and evolve within a set of relatively simple rules. This generative
130 approach is important because interpretations of Holocene palaeoecological data must
131 necessarily consider whether the signal has been perturbed, or is even dominated, by human
132 action. In such contexts, models are tools designed to represent and simplify more
133 complicated or complex ecological systems and thus support surrogative reasoning
134 (O’Sullivan and Perry, 2013). Surrogative reasoning implies a feedback between model and
135 understanding, with failure to close the reasoning loop resulting in “merely replicating field
136 data *in silico*” (Premo, 2007, p. 30). Thus, models are not, at least in this context, of interest
137 simply of themselves, but have value to the extent that they inform us about the system or
138 phenomenon of interest. Lake (2015) argues that to be successful, experimental generative
139 modelling will need to be grounded in theory (so moving primacy away from the data
140 required for parameterization) and, by design, adopt an exploratory approach to model
141 evaluation.

142

143 Generative modelling relies on disaggregated disaggregated, process-based models whereby
144 the overall structure emerges from the activities of and interactions between individual
145 elements of interest. Agent-based models (ABMs) typify this approach and have begun to be
146 used across a broad range of the natural and social sciences (Heppenstall et al., 2012;
147 Railsback and Grimm, 2012; Wurzer et al., 2015). In the ABM framework, the dynamics of
148 systems are represented by considering the basic entities (the ‘agent’) and evaluating how
149 interactions between these agents and their environment result in the formation of system-

150 level (macroscopic) structure; in other words, it is ‘bottom-up’. In such models ‘agents’ are
151 entities that seek to fulfil some goal (e.g. capture resources, breed) and have some level of
152 autonomy (that is their behaviour is not hard-coded and may vary between individual agents).
153 While agents may be individual organisms, they might equally represent households, wider
154 family groups, settlements or even entire tribes. Simulation models developed by ecologists
155 to explore past human-environment interactions tend to have taken a rather different approach
156 in which human agency is not directly represented but is instead mimicked by changes in
157 parameterization (e.g. increased fire frequency or browsing) with the biophysical
158 environment represented in detail (as per the case-studies described below). The flexible
159 representation and emergent behaviour possible with ABMs is especially important given that
160 feedbacks between humans and ecosystems are reciprocal rather than uni-directional
161 (Bowman et al., 2015; Wainwright and Millington, 2010). This point highlights the main
162 weakness of a static representation of human-environment interactions, which that it fails to
163 capture their reciprocal nature: as human action changes the landscapes they inhabit so to
164 human behaviours change in order to adapt to the new conditions (Wainwright, 2008).

165

166 Except for a few specific cases (Griffith et al., 2010), however, ABMs seem to have received
167 little attention in ecologically focussed reconstructions of human-environment interactions.
168 Conversely, the use of ABMs by archaeologists is growing (Cegielski and Rogers, 2016), and
169 the most iconic prehistoric human-environment ABM – the Artificial Anasazi model – was
170 developed by archaeological researchers (Axtell et al., 2002)¹; in such models human
171 decision-making is represented in detail but the biophysical environment often less so. This
172 difference in approach probably reflects the underlying differences in the foci and intellectual

¹ Available at: <https://www.openabm.org/model/2222/version/2/view>

173 traditions of different disciplines². Ultimately, understanding how humans and environments
174 interact in the past is likely to require an explicit representation of human agency.

175

176 **Modelling as experiment**

177 Dowling (1999, p. 261) makes it clear that the use of simulation models is, both epistemically
178 and practically, a form of experiment:

179 *A scientist running a computer simulation performs an experiment upon a theory.*

180 *An abstract, mathematical model of a physical system is implemented on a*

181 *concrete machine. Through that machine, the model can be manipulated as if it*

182 *were a physical experimental target. The mathematical model can then be*

183 *approached and analyzed using skills traditionally associated with experimental*

184 *work: visual observation, "tinkering" with the machine, and intuition about the*

185 *behavior of the concrete system.*

186

187 This view of ‘simulation as experiment’ is appealing for the historical sciences (*sensu*
188 Cleland, 2001) because in such cases adopting the classical hypothetico-deductive scientific
189 framework is infeasible (Biondi, 2014). Direct manipulation of the past is impossible, and
190 the data describing the ecosystems of the past are usually spatio-temporally patchy and
191 provide only indirect representations of the processes of interest. As a result, palaeoecology
192 has relied heavily on pattern identification and diagnosis, but there is a bound to the
193 inferences that can be made from pattern description alone (Birks, 1993; McIntire and
194 Fajardo, 2009). A first concern with inference grounded in patterns is in nature of the patterns

² It is worth noting that ecologists have used individual-based models (IBMs) since the 1960s, especially in the area of forest dynamics. The differences between IBM and ABM are largely semantic and reflect disciplinary traditions; both approaches have the same underlying bottom-up approach.

195 themselves. For example, Blaauw (2012) highlights the risk of circularity in the diagnosis of
196 pattern, especially in cases where multiple proxies are matched or tuned against each other
197 based on the assumption that events seen in them are synchronous. The problem posed by
198 equifinality – that is, the same pattern can arise from many different processes – places a
199 limit on the strength with which inferences about generating process can be made from
200 spatial or temporal patterns alone (Beven, 2006). A classic example of this problem in the
201 palaeoecological literature is the long-standing debate over the mid-Holocene decline of
202 *Ulmus* in northern Europe (Parker et al., 2002). Because this decline occurred around the
203 time of the Mesolithic-Neolithic transition and associated agricultural expansion it is
204 plausible that human activity played a role; on the other hand it is also plausible that a
205 pathogen or regional drought or some combination of all three were responsible. Analysis of
206 patterns alone cannot, of itself, distinguish between these causal explanations.

207

208 Generative simulation models provide tools for experimentation on the past and for testing
209 hypotheses and counter-factual arguments (“how might the system have responded if...?”,
210 Millington and Wainwright, 2016). As McIntire & Fajardo (2009) argue, making robust
211 statements about the dynamics of systems to which we have only restricted access (in space
212 and time) requires ecologists focussed on pattern analysis to adopt a more deductive
213 framework. This argument is echoed in Lake’s (2015) observation that successful generative
214 modelling needs to be grounded in an experimental approach. Despite the appeal of a
215 generative modelling approach to make more of palaeoecological data describing human-
216 environment interaction the approach seems under-used; instead, one of the main uses of
217 palaeoecological information (such as pollen and charcoal records) by ecological modellers
218 has been to ‘validate’ their models (Anderson et al., 2006; Birks, 1993; Iglesias et al., 2015).
219 Ultimately, these validations are used to justify, via induction, a model’s extension to

220 assessing the future. However, how much process-pattern links in the past will apply in a
221 potentially ‘no-analogue’ future is unclear, and hence the use of phenomenological
222 representations of the past to predict the future is fraught with problems (Gustafson, 2013;
223 Haywood et al., 2011; Williams and Jackson, 2007). This type of validation is also fraught
224 where the types of circularity discussed by Blaauw et al. (2012) may be present; if a model is
225 built ‘knowing’ what the interpretation of the palaeoecological data should be (albeit perhaps
226 only implicitly), it is not surprising that validation via model-data confrontation is successful
227 (echoing the concern of Premo, 2007 that modelling can reduce to the simple reproduction of
228 field data). Finally, as Anderson et al. (2006) note, this validation-focussed approach is uni-
229 directional in that the data inform the model but not the other way around; such a narrow
230 application restricts what might be learned both from the data and the model.

231

232 **Use of data and models in palaeoecology**

233

234 *Experimenting with simulation models using (palaeo)ecological data: controls and patterns*

235

236 1. A need for nulls

237 At the heart of classical experimentation is the idea that the effect of process x in some
238 system can be identified by manipulating it and holding all others constant. Thus,
239 quantifying the effect of x requires a control that serves as a point of reference. This type of
240 approach is problematic for natural systems (Diamond, 1983) and is effectively impossible
241 for past ones (Cleland, 2001). However, developing simulations in which processes of
242 interest are deliberately excluded provides a valuable null model that can act, in some ways,
243 as a ‘control’ (Lake, 2015). In their horizon-scan of 50 pressing questions for

244 palaeoecologists, Seddon et al. (2014) identify both the need for a more experimental
245 approach (their Q 49) and a closer consideration of the use of null models (their Q 25) as
246 important. Although Seddon et al. (2014) emphasise statistical models in supporting those
247 advances, the experimental use of simulation models can play an important role in both.

248

249 As an example of how simulation models can support the development of null models,
250 consider the question ‘how much can fluctuations in proxy records be attributed to exogenous
251 drivers as opposed to statistical variability?’ or, to turn this around, ‘what would proxy
252 records look like if they were just stochastic time-series?’. Blauuw et al. (2010) show that
253 patterns visually similar to those in ‘real’ proxy records can arise from random walk
254 processes (Fig. 1). That a process-free algorithm can generate patterns difficult to distinguish
255 from proxy records again evokes the perils of equifinality. Likewise, both Rhode et al.
256 (2014) and Davies et al. (2016) show how changes in the temporal distribution of dated (e.g.
257 ^{14}C) records, which are often assumed to represent patterns in human occupation of the
258 landscape (similar to those observed in the field), can emerge in the absence of any
259 underlying change in human demography or behaviour. A second context where neutral
260 models are useful is in understanding the generation of landscape-level vegetation patterns.
261 Succession-disturbance dynamics are affected by the spatial structure (composition and
262 configuration of elements) of the landscapes in which they occur (Turner, 2010). Therefore,
263 when developing representations of palaeoecological processes, it is not necessarily sufficient
264 to consider just the composition of a landscape as established from pollen records; often the
265 spatial *pattern* must also be examined. Understanding the implications of changes in
266 landscape configuration is particularly important when trying to identify human activity, as
267 prehistoric humans *dynamically* changed the processes shaping the landscape mosaic, and
268 this change in landscape pattern alone may result in changes to ecological processes

269 (Delcourt, 1987). The dynamic nature of landscape change is crucial and is a potential source
270 of equifinality as, for example, the same outcome may not occur for the same change because
271 of internal and external dynamic interactions. As we argued above, such multifaceted links
272 between pattern-process are unlikely to be adequately captured in static representations of
273 human-environment interactions. Detailed methods do exist to reconstruct landscape
274 composition and structure from pollen records (e.g. the LRA, Sugita, 2007a, 2007b; Sugita et
275 al., 2010), but these are data-demanding, require extensive calibration against modern data
276 and are taxa- and site-specific. A neutral landscape model (NLM) approach, in which a wide
277 variety of landscape patterns are simulated but with the same statistical characteristics, can be
278 used to test the potential influence of landscape pattern on past ecological processes
279 (Etherington et al., 2015). Importantly for palaeoecological applications, NLMs can be
280 constructed such that the known proportional composition of a landscape in a pollen
281 catchment can be embedded within a broader unknown landscape pattern to examine the
282 possible influence of patterns in the wider landscape (Fig. 2). The Multiple Scenario
283 Assessment (MSA) approach described by Bunting and Middleton (2009) is somewhat
284 similar in that it starts with observed pollen records and then generates multiple candidate
285 simulations of the landscape structure that might have produced them. Running repeated
286 simulations on landscapes of the same composition, but with different spatial configurations,
287 allows an experimental assessment of the importance of both initial conditions (enabling
288 contingency and sensitivity issues to be evaluated) and space in ecosystem dynamics. Thus,
289 the use of neutral models can provide a frame of reference for detailed palaeoecological
290 records (a point emphasised by Barton et al., 2016), and with careful *in silico*
291 experimentation partition the contribution of different drivers to observed dynamics.

292

293 2. Making better use of ‘patterns’

294 The inferences made using any model will depend on its adequacy, which is a context-
295 dependent quality. Most methods designed to assess model adequacy rely on the
296 ‘confrontation’ of a given model with some (independent) data (Beck, 1987; Hilborn and
297 Mangel, 1997; Mayer and Butler, 1993; Mulligan and Wainwright, 2004). Putting to one side the
298 fact that models are false by definition, Oreskes et al. (1994) argued that models cannot be
299 verified (i.e. found ‘true’)³ simply by pattern matching; even if a model manages to perfectly
300 (or even adequately) mimic some target data-set, other parameterizations or models may
301 perform equally well (i.e., there is a problem of under-determination). A second, but related,
302 problem with model-data confrontation is that it tends to emphasize parameter uncertainty in
303 a fixed model structure, whereas in reality structural (epistemic) uncertainty (i.e. the way in
304 which specific processes are represented in a model) is likely to be as acute, if not more so.

305

306 Partly in reaction to their concern over the *ad hoc* nature of the development of complex
307 simulation models, Grimm and Railsback (2005; 2012) advocate pattern-oriented modelling
308 (POM). At its heart, POM is based on the view that the patterns observed in complex
309 systems (strictly, in the data describing them) are the fingerprints of the processes that
310 generated them. In terms of model evaluation, these patterns act as filters that can be used to
311 assess if a model is adequate in its parameterisation and/or its structure (Fig. 3). A key facet
312 of POM is the use of *multiple* patterns; it is more difficult for a model to agree with multiple
313 weak patterns than with a single strong one. Thus, for a model to be deemed adequate it will
314 need to be able to reproduce a number of observed patterns. The POM approach is not
315 concerned with isolating a single ‘true’ model; rather it seeks to identify the *set* of models
316 that have sufficient structural realism and adequate parameterization to meet specific targets.

³ It is worth noting that Oreskes et al. use a natural language definition of verified that is distinct from what the term is usually taken to mean in a computer-science framework.

317 There are two compelling arguments for the use of POM approach for palaeoecological data
318 and models. First, as described above, a wealth of patterns describing (socio-)ecological
319 systems of the past are now available, and, second, the use of *multiple* patterns to evaluate
320 models is crucial in settings where the likelihood of either equifinality or trajectory
321 divergence (i.e. the same parameter set generating a broad range of outcomes) is high, as it is
322 in historical settings reconstructed via proxy data (Bunting and Middleton, 2009; Gerbault et
323 al., 2014; Janssen, 2009; Stiner, 2008). Thrippleton et al. (2014) provide an example of the
324 use of a POM framework to inform the parameterization of a dynamic vegetation model
325 (LANDCLIM) that was used to explore successional change following the Taupō eruption of
326 c. 232 CE (North Island of New Zealand). Horrocks and Ogden (1998) described two
327 important patterns in the post-eruption succession: (1) conifer dominance in the period
328 immediately after the eruption (in particular by *Libocedrus bidwillii*) and (2) a subsequent
329 spread of *Weinmannia racemosa* in montane areas. These patterns were framed as
330 quantitative criteria and a full parameter-space sweep conducted for two highly uncertain but
331 critical life-history parameters – maximum growth rate and shade-tolerance – with only those
332 parameterizations that met these criteria retained. When the model was assessed against the
333 pollen record it could reproduce a series of patterns seen in the pollen records and in the
334 modern vegetation (e.g. vegetation composition and elevational zonation). If a model that
335 has passed a POM assessment then generates previously unobserved patterns then those can
336 stimulate further empirical investigation and hypothesis testing (Grimm et al., 2005; Wiegand
337 et al., 2003). An important challenge in the application of POM for palaeoecological models
338 is that the state variables of models are not expressed in units similar to those of the proxies
339 being used. For example, vegetation models may predict biomass or species abundance, but
340 pollen records are expressed in concentrations that may or may not be easily mapped to
341 biomass or abundance. Developing palaeoecological models that produce virtual natural

342 archives (see Barton et al., 2016) will be important if tools such as POM are to be more
343 effectively used. Alongside the development of virtual records ongoing advances in our
344 ability to link proxy information to the underlying mechanisms generating it (e.g., Dawson et
345 al., 2016; Higuera et al., 2007 provide examples with fossil pollen and charcoal, respectively)
346 will also help to strength the inferences derived from a POM approach.

347

348 A key challenge in POM is in deciding what for any given model ‘adequate’ actually means.
349 Tools developed by statisticians to assess model adequacy, for example arising from multi-
350 model inference (Burnham and Anderson, 2002), are now being applied to ecological simulation
351 models (Hartig et al., 2011). Such tools facilitate a rigorous, robust and repeatable “tinkering
352 with the machine” to use Dowling’s (1999) phrase. For example, Approximate Bayesian
353 Computation (ABC: Beaumont, 2010; ABC, Csilléry et al., 2010; Stumpf, 2014), which has
354 been used to parameterize and select between population genomic models (e.g. Fagundes et
355 al., 2007 use ABC to select between different models of human origin and migration from
356 Africa), is beginning to be applied to complex ecological simulations (Morales et al., 2015;
357 van der Vaart et al., 2015). In essence, ABC involves having some form of target data (a
358 pattern, or more usually a suite of summary statistics describing multiple patterns) and then
359 running many simulations with parameters sampled from broad uninformative (‘prior’)
360 distributions and model structure varied. Those simulations that are sufficiently close to the
361 targets are retained and provide an updated (‘posterior’) estimate of the parameters included
362 in the model and also an indication as to the weight of support for alternative model
363 structures (e.g. via Baye’s factors, Beaumont, 2010). The simplest ABC estimation method is
364 a reject-accept algorithm in which some threshold distance between model and observation is
365 set and only those simulations within that tolerance retained or, alternatively, the model is run
366 until some pre-determined number of simulations fall within that threshold (see Fig. 4).

367 However, other more sophisticated approaches, such as sequential Monte Carlo filters in
368 which the parameter space is searched in a biased way to focus on more informative parts of
369 it, are likely more efficient for complicated simulation models (Stumpf, 2014). Again, the
370 wealth of patterns available to palaeoecologists – coupled with the increasing accessibility
371 and availability of high-performance computational infrastructure – makes ABC-type
372 approaches relevant to model-based exploration of human-environment interactions in the
373 past. The ability to filter different model structures is crucial given the critique that ABMs
374 are prone to being overly complex, making it difficult to identify the processes and
375 parameters that drive them and hence communicate their outcomes effectively (Lee et al.,
376 2015).

377

378 **Modelling human-environment interactions in the past: nulls, patterns and experiments**

379 Much of the discussion above could be related to nearly all ecological and environmental
380 contexts. So, how do these arguments and approaches apply to the simulation of the
381 dynamics of human-environment interactions in past environmental systems? Reconstructing
382 environments from proxy information such as fossil pollen and charcoal requires a robust
383 understanding of how those records are formed: where does the pollen preserved at a given
384 site come from? from which taxa? what is the relative contribution of the local vs. the
385 regional species pool? what is the relative importance of extrinsic (top-down) and intrinsic
386 (bottom-up) forcing factors? And in the context of understanding how humans affected the
387 processes described by these proxies questions of agency and social structure become central.
388 In this section, we consider, how generative simulation modelling can inform our
389 understanding of such questions, especially as they relate to human agency and decision-
390 making. We do not review the methods themselves in depth – they have been thoroughly
391 described elsewhere (Epstein, 2006; Heppenstall et al., 2012; O’Sullivan and Perry, 2013;

392 Wurzer et al., 2015) – rather our focus is on the types of inferences made from models in
393 each of these examples.

394

395 *‘Behaviourally neutral’ nulls*

396 In the context of understanding human-environment interactions, an obvious question is
397 whether human activity was necessary to generate some observed pattern of interest.
398 Because the presence of humans and their activities are often reconstructed indirectly (e.g.
399 from abrupt changes in ecological conditions or from changes in the distribution of specific
400 materials/dates) a more specific question is ‘how likely are such patterns in the absence of
401 humans?’ Evaluating this question is not possible without explicit recourse to a model of
402 some form, and as Barton et al. (2016 p. 38) comment “...the ability to conduct such
403 contrafactual ecological dynamics (i.e., a Holocene world without humans) is a little
404 discussed but uniquely important contribution of this kind of modelling that is impossible
405 with the analysis of prehistoric empirical data alone.” Null simulation models provide a
406 powerful way to evaluate such questions; a good example of this type of approach is provided
407 by the random walk models of pollen records and associated forcing factors of Blauuw et al.
408 (2010) described earlier (Fig. 1). Likewise, Brantingham (2003) showed how an agent-based
409 model with minimal (zero) representation of human agency and environmental structure can
410 generate plausible patterns of lithic assemblages. In the specific context of human-
411 environment interactions the “behaviourally neutral” model of Davies et al. (2016) of the
412 formation and preservation of surface archaeological deposits (e.g. fire-pits and hearths) in
413 arid Australia is informative. In these landscapes the temporal density of surface deposits
414 varies and this could be interpreted as evidence for changes in human presence/activity; in
415 particular, the records exhibit occasional long gaps and an increase in density towards the
416 present. Davies et al. (2016) used an agent-based model to evaluate how such records might

417 be produced in the absence of human agency (the agents leave surface deposits at a constant
418 rate and with no spatial structure). This simulation experiment, therefore, provides a null
419 expectation against which to evaluate empirical data. The outcome of the experiment was to
420 demonstrate that time-varying geomorphic processes act to reveal and preserve deposits and
421 so, of themselves, generate such patterns. This model-derived outcome suggests that even
422 though human activity was important in the landscapes considered, and its intensity varied
423 through time and space, directly linking this to the available patterns is not straightforward.
424 This result does *not* mean that humans had no role in generating the observed pattern, but it
425 does suggest that the *a priori* assumption that they are solely responsible for this pattern is
426 questionable (as, for example, demonstrated by Wainwright, 1994 in the case of post-
427 depositional movement of artefacts at archaeological sites).

428

429 If human activity is established as an important driver of ecosystem change, then
430 understanding the implications of their behaviour for systems dynamics becomes central. As
431 an aside, an interesting issue in this context is whether the appropriate null for human
432 decision-making is the 'zero intelligence agent' or the entirely rational and informed "*Homo*
433 *economicus*" of classical economics (Bentley and Ormerod, 2012); most neutral models of
434 human-environment interaction developed by non-economists have favoured the former. For
435 example, soon after human arrival in NZ in the late 13th century CE (Wilmshurst et al., 2008)
436 widespread deforestation took place as a result of anthropic fire. However, the motivation
437 behind this event remains unclear, and cannot be elicited from palaeoecological information
438 alone. Using a spatial simulation model, which incorporated successional change, fire and
439 feedbacks between fire and vegetation age, Perry et al. (2012) showed that in the absence of
440 human fire, the transformation was extremely unlikely (a null model of no humans) and
441 would not have occurred if human ignitions were spatio-temporally random (a null model of

442 uninformed ignition). However, their model experiments also suggest that fire-vegetation
443 feedbacks made the transformation almost inevitable once started, suggesting that such
444 dramatic changes might not have been intended even if anthropic fire was deliberate. Of
445 course, the ability of these models to reproduce a suite of patterns does not ‘prove’ that this is
446 how these transformations unfolded, but it does generate a range of hypotheses amenable to
447 experimental testing (e.g. testing whether the postulated fire-vegetation feedback mechanisms
448 inherent in this explanation do exist). Furthermore, the model Perry et al. (2012) used is
449 phenomenological rather than mechanistic, and so it is important to develop a process-based
450 understanding of the underlying feedbacks if these dynamics are to be confirmed; neither
451 proxies nor phenomenological models can generate such causal understanding. Developing
452 simple representations of human behaviour and agency is a powerful way of “generating
453 inferences about how the world could have been, rather than about how the world is” (Premo,
454 2006, p. 108). The key point here is that neutral models can guide our understanding of what
455 to expect if specific behaviours potentially responsible for generating observed patterns and
456 trajectories are omitted from a model.

457

458 *Making better use of patterns*

459 Crema et al. (2014) used a rejection-tolerance ABC approach to parameterize and select
460 between three different models of cultural transmission as preserved in the archaeological
461 record. In the apparent absence of the use of ABC to evaluate simulation models of past
462 human-environment interactions this study provides a useful, and somewhat related example
463 of the strengths of the approach. The specific context considered by Crema et al. (2014) is
464 the temporal change in arrowhead form during the Neolithic (data from western Europe).
465 Crema et al. consider three candidate models and their parameterization: 1) a model of
466 unbiased transmission; 2) a model of conformist bias; and 3) a model of anti-conformist bias.

467 The first of these three is a null model in that it assumes the probability of a variant being
468 adopted is proportional to its current abundance; the other two models are biased either in
469 favour of more (2) or less (3) widely used variants. The empirical data provide a target
470 pattern, which is the dissimilarity in assemblage form between two successive periods.
471 While the archaeological details are not relevant here, what is important is the ABC approach
472 that Crema et al. (2014) adopt was able to parameterize the models adequately, but could not
473 isolate a single ‘best’ model, with both the unbiased and conformist model equally plausible.
474 While this may seem inferentially unsatisfactory, it does quantify the risk of equifinality in
475 the data in a way that an *a priori* assumption of the ‘best’ model structure cannot⁴. The
476 approach of Crema et al. (2014) is clearly applicable to a wide variety of palaeoecological
477 settings where proxy records provide a range of summary statistics to inform the approach.
478 The availability of multiple proxies is particularly useful for ABC because it provides
479 potentially somewhat independent filters for the algorithm.

480

481 *Experiments and scenarios*

482 A common use of simulation models is to explore counterfactual (‘what if...?’) scenarios,
483 and there has been some use of this approach in understanding past human-environment
484 interactions (Wainwright and Millington, 2010). Here we consider two contrasting examples: (i)
485 the use of a dynamic vegetation model (LANDCLIM) supported by palaeoecological proxy
486 data to explore the effects of land-use change and fire on vegetation in ecosystems in western
487 Europe (Colombaroli et al., 2010; Henne et al., 2013) and (ii) the use of an agent-based
488 model of landscape change (CybErosion) that directly represent human decision-making, as

⁴ Although this outcome may also arise from Crema et al. using just a single summary statistic (i.e. pattern), rather than the multiple targets inherent in POM (Grimm and Railsback, 2012) and advocated in the technical ABC literature (Rasmussen and Hamilton, 2012).

489 well as geomorphic and ecological processes (Wainwright, 2015). Our emphasis is not on a
490 detailed description of the outcomes of these experiments *per se*, but rather on the way in
491 which they were used and the types of inference developed from them.

492

493 Colombaroli et al. (2010) and Henne et al. (2013) used the LANDCLIM model to explore
494 how changes in vegetation at Gouillé Rion (Swiss Alps) and Lago di Massaciuoli
495 (Tuscany), respectively, over the Holocene might relate to shifts in climate and changes in
496 human activity. The LANDCLIM model is a detailed representation of vegetation dynamics
497 (succession and multiple disturbance types) at high spatial resolution (25×25 m); the model
498 is described in detail in Schumacher et al. (2004). Interactions between disturbance and
499 climate are dynamic and emerge from the model, but it does not directly include human
500 behaviour; rather Colombaroli et al. (2010) and Henne et al. (2013) mimic human actions by
501 changes in parameterization (e.g. increased in fire frequency at given times). Colombaroli et
502 al. (2010) and Henne et al. (2013) used model scenarios, supported by temperature
503 reconstructions, to evaluate how the patterns seen in detailed multi-proxy palaeoecological
504 records (pollen, plant remains, charcoal) might have arisen. For example, Henne et al. (2013)
505 systematically explored the effects of browsing and fire by simulating three levels of each
506 (nine experimental treatments in total). Both studies strongly suggest that the temporal shifts
507 in vegetation seen in the proxy records are only likely to have occurred under increased
508 human land activity. Wainwright (2015) used an agent-based model (CybErosion) that
509 represents interactions between Mesolithic hunter-gatherers and Neolithic agriculturalists and
510 their environment, including processes such as livestock husbandry and browse, fire and
511 erosion and the feedbacks between them in a semi-mechanistic way. Using this model,
512 Wainwright (2015) explored three different scenarios in which human pressure on the
513 landscape varied from low environmental pressure/low invasion rate/extensive agricultural

514 production to high pressure/high invasion rate/intensive agricultural production. An
515 important outcome of these experiments was that changes in landscape connectivity can
516 result in periods of stability and instability (the stability-instability-connectivity [SIC] model)
517 without such transitions being directly represented (i.e., it is ‘emergent’), but the trajectories
518 seen in the different scenarios suggest that these SIC dynamics can take a variety of forms.

519

520 While bearing in mind that they come from different disciplinary perspectives (palaeoecology
521 vs. geoarchaeology), it is informative to compare how these two case studies use *in silico*
522 experiment to make inferences about past human-environment interactions. Colombaroli et
523 al. (2010) and Henne et al. (2013) start with detailed palaeoecological reconstructions of two
524 specific sites and their associated taxa, and seek to use the model to identify the mechanisms
525 that may have generated the patterns observed in those records. Although they invoke human
526 activity in the form of changes in fire regime and browsing, they do not directly represent
527 them – rather humans are treated as ‘boundary conditions’ with parameterization changed
528 accordingly (e.g. fire frequency increased tenfold to represent increasing human intensity in
529 the landscape). This approach yields a detailed, and partially mechanistic, understanding of
530 biophysical change in a specific landscape. On the other hand, Wainwright (2015) starts with
531 the general observation that there are periods of both landscape stability and instability during
532 the Neolithic in western Mediterranean Europe, and asks how they arise. He explores this
533 question with an agent-based model (ABM) that explicitly represents human decision-making
534 and biophysical change and evaluates the implications of a suite of assumptions, framed as
535 scenarios describing different rates of human movement and agricultural intensity (Figure 5).
536 While Wainwright (2015) does not do so, the types of virtual archive produced by process-
537 oriented ABMs could be evaluated against proxy records such as fossil pollen (the caveats
538 described earlier notwithstanding). This style of modelling demonstrates how feedbacks

539 between humans and the environment can generate a rich range of dynamics (in this case by
540 altering the nature of connectivity in the landscape), but it does not focus on a specific site or
541 suite of taxa. It is important to emphasise that neither approach to modelling is inherently
542 ‘better’ – the usefulness of an approach depends on the purpose of the modelling activity –
543 but, on the other hand, modellers cannot have it both ways; there will always be trade-offs
544 between precision, realism and generality (Levins, 1966).

545

546 **Where next?**

547 Increasing computational power and data availability are rapidly changing the way that
548 simulation is practiced in the natural and social sciences (Gattiglia, 2015; Lazer et al., 2009;
549 Sellars et al., 2013). However, as noted in our examples above, technological increases will
550 not solve all of the challenges associated with representation and scale with which ecologists
551 struggle. In the specific area of modelling prehistoric human-environment interactions, we
552 briefly consider two areas ripe for development from an ecological perspective: (i) the use of
553 ABMs and (ii) improvements in the ways that model outcomes are communicated and
554 interpreted.

555

556 *Agent-based approaches*

557

558 We are not arguing that an ABM approach is the best option for all questions, and whether
559 they will “make revolutionary advances within the overall archaeological research paradigm”
560 as some have argued (Cegielski and Rogers, 2016, p. 284) remains to be seen. O’Sullivan et al.
561 (2012, p. 120) argue that there are three conditions where ABMs are likely to be useful: (i)
562 the environment is heterogeneous in space and time, (ii) the agents interact in the decision-

563 making process and (iii) the system is middle-numbered (that is too many elements to be
564 open to purely deterministic analysis but too few for the laws of statistical physics to apply,
565 Weaver, 1948). While these conditions may well be true of many settings where human-
566 environment interactions are being represented, they are not universal. ‘Fast and frugal’
567 models (Carpenter, 2003) still have an important role to play in (initial) explorations of
568 system behaviour (e.g. see Holdaway and Jacomb, 2000; Perry et al., 2014 in the context of
569 hunting pressure required to drive moa to extinction). ABMs can also, but do not have to, be
570 data-hungry and require extensive parameterisation and testing (especially if arguments about
571 system properties such as ‘emergence’ are to be made); for example the simplified version of
572 the CybErosion ABM used by Wainwright (2015) still requires 35 parameters to be estimated
573 (see his Table 5.2). In such cases, the POM approach supported by computational methods
574 such as ABC have important roles to play. As with all areas of ecology the appropriate
575 complexity (i.e. number of parameters and processes included) of a model is very much a
576 function of the purpose of the modelling exercise (Evans et al., 2013; Levins, 1966). A final,
577 important, question is whether the growing use of ABMs among those concerned with the
578 ecological and social systems of the past will generate robust and testable theory or will
579 simply generate a proliferation of empirically-detailed but idiosyncratic models (a concern
580 expressed by Grimm, 1999; O’Sullivan et al., 2016).

581

582 *Visualisation and communication*

583 As noted earlier a recurrent critique of palaeoecology has been its reliance on ‘story-telling’
584 rather than the ‘stronger’ types of inference (Biondi, 2014) made in other areas of the natural
585 sciences. There has been a long debate over the virtues, or otherwise, of how the historical
586 sciences construct knowledge and this is beyond the scope of our review (but see, Cleland,
587 2001, 2011). However, it is becoming apparent that generative simulation models offer much

588 more than shallow systems descriptions derived from quantitative syntheses of the data they
589 produce (Winsberg, 2010); for example, there is growing interest in the view that simulation
590 models are themselves narrative devices and their outcomes can be communicated in that
591 way (McGlade, 2014; Millington et al., 2012). The use of simulation models in the context
592 of understanding past human-environment interactions has the potential to mediate between
593 the desire for strong and robust inferences and the historical nature of the data
594 palaeoecologists use to make such inferences. Using models to develop ‘thick’ descriptions
595 (Millington and Wainwright, 2016) could take the form of narrative, or it could take the form of
596 sophisticated visualization of the landscapes of the past (Caseldine et al., 2008; Edwards et
597 al., 2015). Narrative explanations will require generative models that adequately capture
598 feedbacks between social and ecological components of systems across multiple spatio-
599 temporal scales (Verburg et al., 2016).

600

601 **Conclusions**

602 The ‘grand challenges’ that palaeoecology and archaeology are engaged with (Kintigh et al.,
603 2014; Seddon et al., 2014) do not simply require more and bigger data, but also new ways to
604 use and synthesize it. However, while simulation modelling has an important role to play in
605 their resolution, this needs to be as more than simply a consumer of data for validation. As
606 we have argued, generative models offer the ability for theory to inform empirical data but
607 also a way to ‘experiment with theory’, and as with any informative experiment, the use of
608 simulations as such should provide new insights and provoke new questions.

609

610 **Author contributions**

611 GP led the writing of the manuscript; all authors made substantial contributions to the
612 development of the ideas presented here and commented critically on drafts of the
613 manuscript.

614

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624

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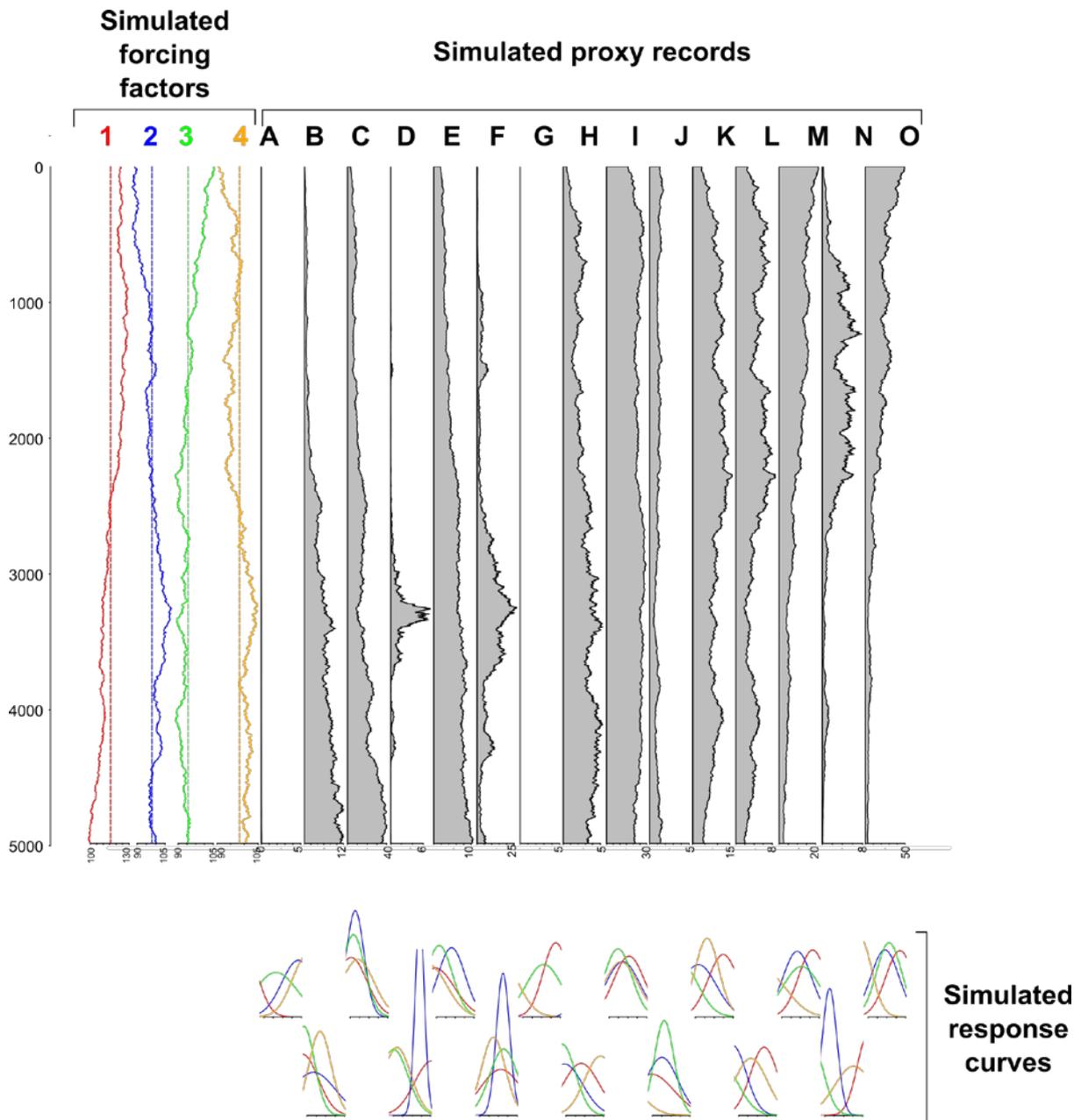
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910 **Illustrative Material**

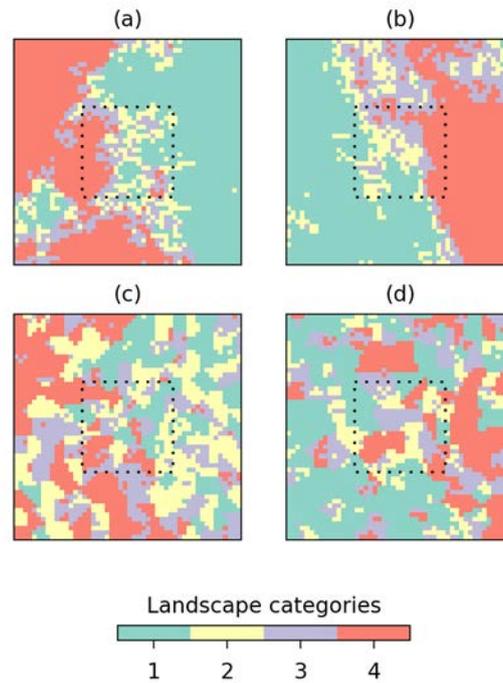
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913 **Figure 1** Sample fossil pollen and exogenous forcing factor records generated with Gaussian and
 914 Poisson random walks. Although these null records show some of the visual hallmarks of ‘real’ proxy
 915 records (e.g. long-term shifts [proxy record O] and short-term spikes [proxy record D] in dominance)
 916 they are entirely random. Figure generated using R code provided in Blaauw et al. (2010).

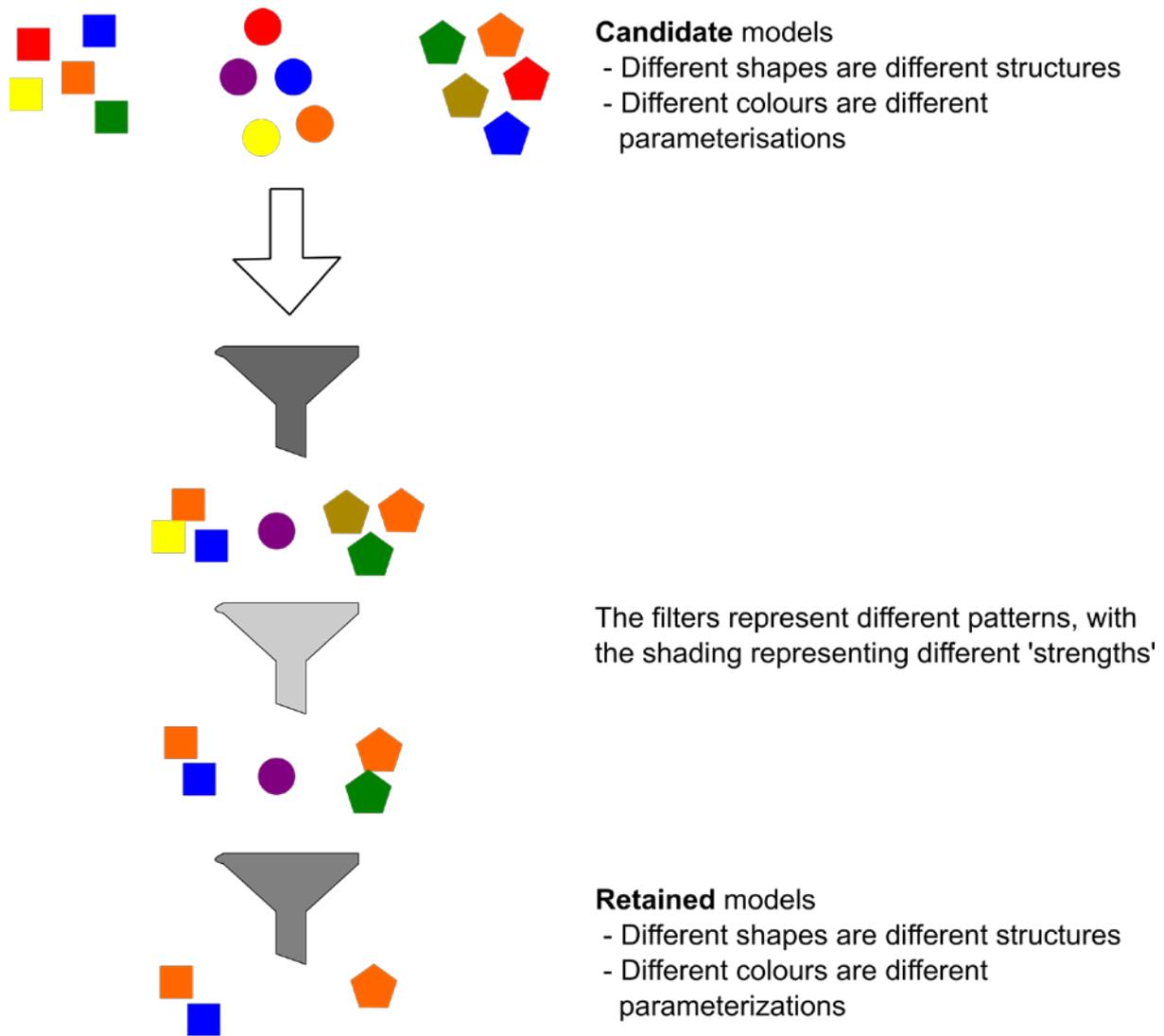
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919 **Figure 2.** Examples of neutral landscape models of prehistoric landscapes for a hypothetical pollen
920 record indicating four landscape categories. (a, b) Different realisations of naturalistic landscapes in
921 which landscape categories are an ordered sequence resulting from a natural environmental gradient.
922 (c, d) Different realisations of human-influenced landscapes in which the original naturalistic gradient
923 patterns have been modified by discrete patches representing localised human disturbance. In all
924 cases the landscape category proportions within the hypothetical pollen catchment area (dotted line)
925 are equally divided amongst the four categories, while the landscape proportions beyond the pollen
926 catchment area vary individually as part of a broader but consistent spatial pattern to represent
927 uncertainty about landscape patterns beyond the pollen catchment area.

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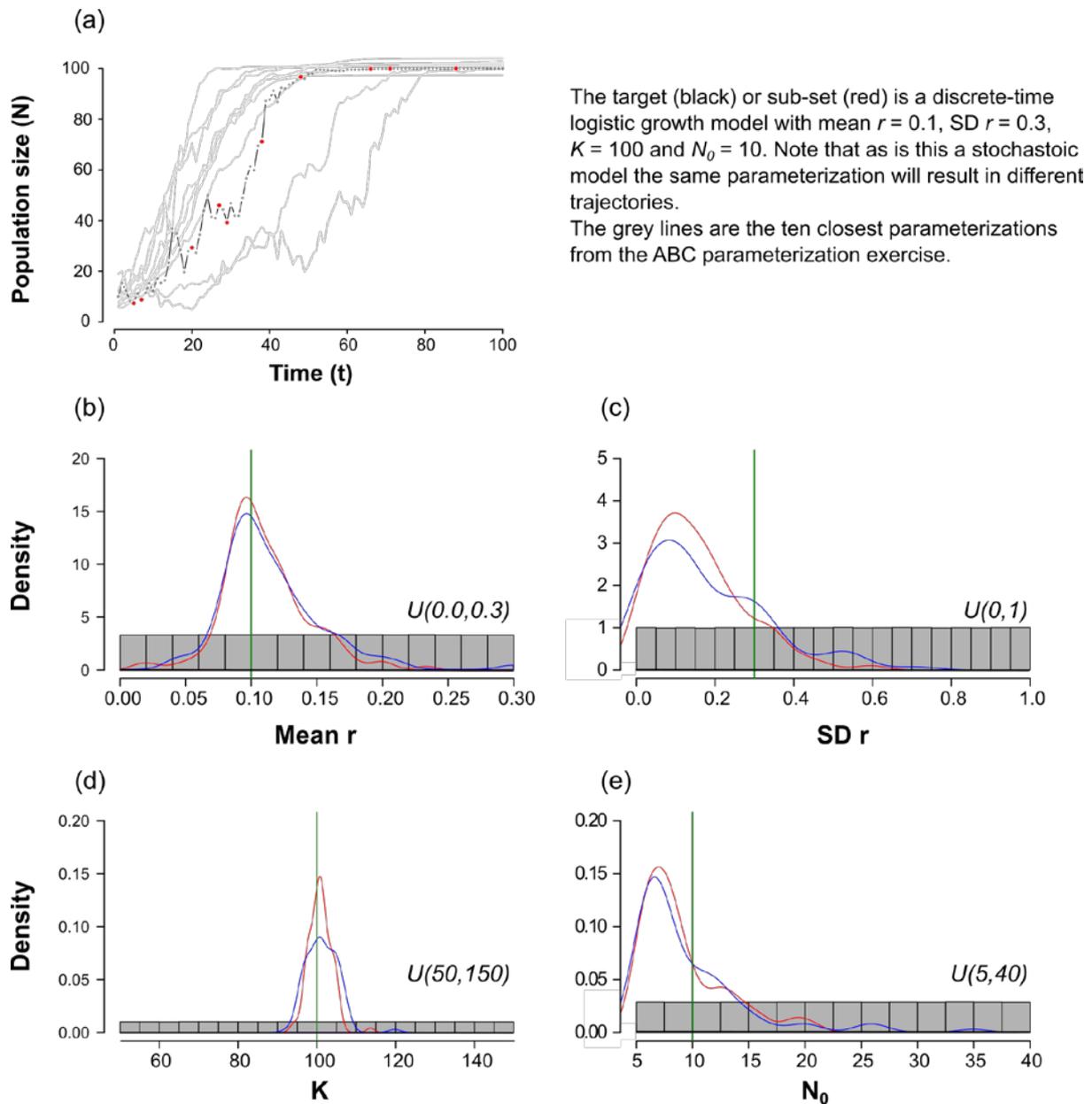
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931 **Figure 3** The pattern-oriented modelling (POM) framework (Grimm et al., 2005; Grimm and
932 Railsback, 2012) is designed to help modellers implement models that contain sufficient structural
933 detail and are adequately parameterised. This evaluation is achieved by comparing a suite of model
934 structures (different shapes in figure) and parameterisations (different colours in figure) and assessing
935 them against a set of target patterns (the filters). POM does not seek to find the single 'best' model;
936 rather it inherently recognises that there may be a suite of adequate models (lower group of coloured
937 shapes) with different structures and parameterisations.

938

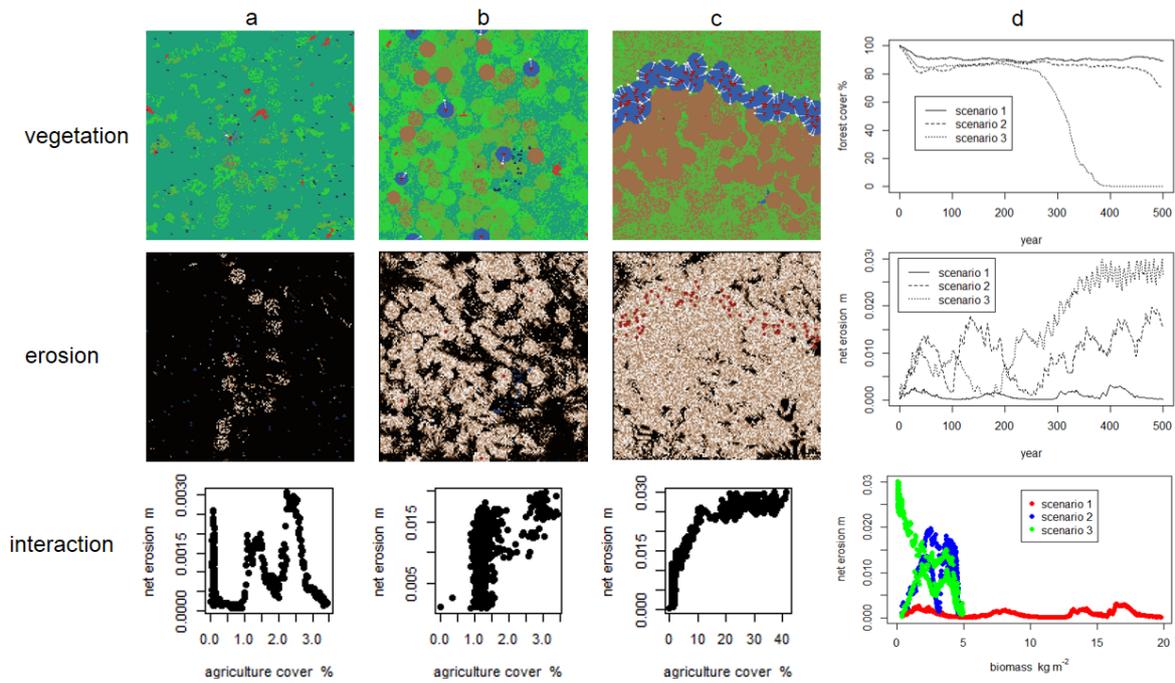
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941 **Figure 4** A simple example of the ABC reject-accept approach. In this example, the ‘target’ pattern is
 942 a population trajectory (a) arising from a discrete-time logistic population model with stochasticity in
 943 the growth term r . There are four parameters we wish to estimate (μ , σ , K , N_0); to do so we
 944 simulate the population model 1×10^6 times, each time drawing values for the four unknown
 945 parameters from a broad uniform distribution (the ‘prior’; grey). For each simulation, we assess how
 946 close the trajectory is to the target (using the summed squared difference across the entire series [red]
 947 and the Euclidean distance [blue] between 10 irregularly spaced observation points). We retain the
 948 100 simulations closest to the observed pattern and the posterior estimates of those parameters is
 949 provided by these retained simulations (b-e). Vertical green lines are the true parameter values.

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952

953 **Figure 5** Output from the CybErosion model showing how vegetation and erosion emerge under three
 954 scenarios (a, b, c) about the nature of human-environment interactions, increasing in intensity and
 955 rapidity from left to right. Each grid cell is 100 m × 100 m in size. Colours in the vegetation maps are
 956 as follows: light, medium and dark green are grass, shrub and forest, respectively; blue areas are in
 957 active cultivation and brown areas were formerly cultivated and are now bare. In the erosion maps
 958 (middle row), rates are scaled from high (white) through medium (brown) to low (black). Column (d)
 959 shows the temporal dynamics of the forest cover and erosion in the landscape (top and middle) and
 960 the relationship between landscape-level biomass and average net erosion (bottom). Figure from
 961 Wainwright. (2015). Reproduced with permission of John Wiley & Sons.

962